

# N58 OpenCPU

## API Notes

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This document provides guide for users to use N58.

This document is intended for system engineers (SEs), development engineers, and test engineers.

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# Contents

1 About N58 OpenCPU .....	7
1.1 Flash Space .....	7
1.2 Basic Functions .....	8
1.3 Development Process .....	8
2 APIs .....	9
2.1 Power Management .....	9
2.2 I/O Interfaces .....	12
2.2.1 UART .....	12
2.2.2 I2C .....	15
2.2.3 SPI .....	17
2.2.4 GPIO .....	18
2.2.5 ADC .....	20
2.3 Peripherals .....	20
2.3.1 Audio .....	20
2.3.2 LED .....	24
2.3.3 Keypad .....	25
2.3.4 LCD .....	25
2.3.5 SD .....	26
2.3.6 Spi flash .....	27
2.4 Services .....	28
2.4.1 Data .....	28
2.4.2 Voice .....	31
2.4.3 SIM .....	33
2.4.4 USSD .....	37
2.4.5 SMS .....	37
2.4.6 Location .....	40
2.4.7 Wi-Fi Scanning .....	43
2.4.8 Network .....	43
2.4.9 FOTA .....	49
2.4.10 Virtual AT .....	50
2.4.11 Socket .....	51
2.4.12 FTP .....	57
2.4.13 HTTP/HTTPS .....	60
2.4.14 BLE .....	65
2.4.15 Standard MQTT .....	69
2.4.16 Alibaba MQTT .....	72
2.4.17 Websocket .....	75
2.4.18 Packet manage .....	76
2.5 System .....	77
2.5.1 Device Management .....	77
2.5.2 Message Queue .....	78

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2.5.3 File Operation .....	80
2.5.4 Thread .....	88
2.5.5 mutex .....	91
2.5.6 pipe .....	92
2.5.7 Semaphore .....	94
2.5.8 Time .....	95
2.5.9 Timer .....	96

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# About This Document

## Scope

This document is applicable to the N58 series.




## Audience

This document is intended for [system engineers \(SEs\)](#), [development engineers](#), and [test engineers](#).

## Change History

Issue	Date	Change	Changed By
1.0	2020-03	Initial draft	Wu Guoqing
1.1	2020-08	Optimized API descriptions. Added some APIs.	Wen Jingshun
1.2	2020-08	Added the file operation APIs	Wen Jingshun
3.0	2021-01	<ul style="list-style-type: none"><li>Added the BLE APIs.</li></ul>	Yang Mengsha
		<ul style="list-style-type: none"><li>Added the MQTT APIs.</li></ul>	Shui Ying
		<ul style="list-style-type: none"><li>Added the APIs used to obtain the socket status, forcibly delete the file folder, set the time synchronization switch, obtain the device boot time, and obtain the hardware version.</li></ul>	Hu Jun
		<ul style="list-style-type: none"><li>Added the websocket APIs</li></ul>	Yang Xiaojun
		<ul style="list-style-type: none"><li>Added the SIM and Network related APIs</li></ul>	Wang Chen Huang
		<ul style="list-style-type: none"><li>Modified the size of storage space</li></ul>	Wei Gang
			Li JinTao

## Conventions

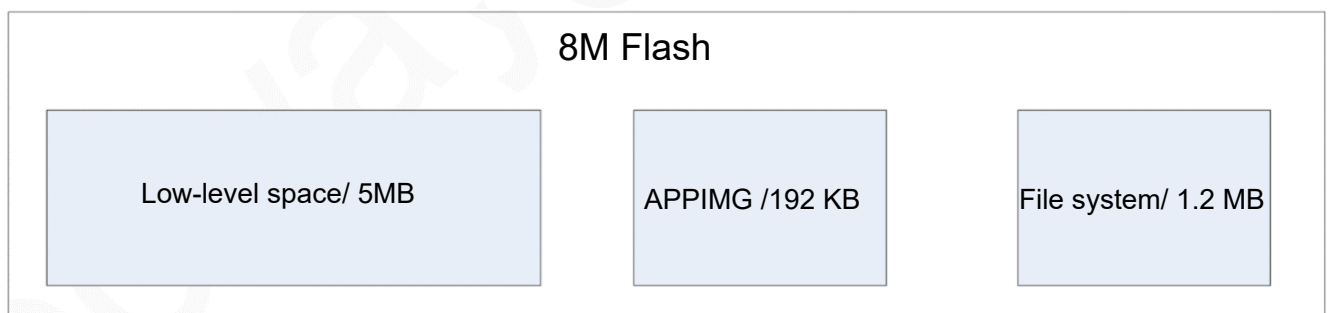
Symbol	Indication
	This warning symbol means danger. You are in a situation that could cause fatal device damage or even bodily damage.
	Means reader be careful. In this situation, you might perform an action that could result in module or product damages.
	Means note or tips for readers to use the module

# 1 About N58 OpenCPU

The N58 OpenCPU module runs FreeRTOS. It mainly provides the following hardware resources.

- ARM Cortex-A5 processor, 500 MHz
- Supports the installation and running of applications that are developed based on libc by C language
- Memory
  - RAM: 128 KB (can be extended to 1 MB)
  - ROM: 192 KB (extend it as required)
  - File system: 1.2 MB
- Supports multiple network modes: GSM/GPRS & LTE Cat1
- Supports various services including GPS, BT, Wi-Fi Scan, etc.
- Supports USB2.0, ADC, UART, SPI, I2C, and GPIO
- Supports key and LCD backlight

## 1.1 Flash Space



- Programming language
  - Neoway provides API functions of RTOS in C language and header files that define relevant data structures.
- Compilation environment
  - Compile an application with the cross compiler provided by Neoway in Windows OS and generate an executable program image.
- Operation method
  - Use the RESEARCHDOWNLOAD tool to flash the executable image into N58, and the program automatically starts with the startup of the system.

## 1.2 Basic Functions

- PPP dialing
- Network related functions
- Voice
- SMS message
- Location
- Wi-Fi scanning
- SIM cards
- Audio
- FOTA upgrade
- Sleep mode
- I/O interfaces including GPIO, ADC, SPI, UART, RTC, I2C, etc.
- Switch of LCD backlight
- Matrix buttons
- Virtual AT functions

## 1.3 Development Process



Process description

1. Read the APPIMG from the flash into the RAM
2. Run the APPIMG

Enter **appimg\_enter**, the entry function of appimg, to run tasks.



## 2 APIs

### 2.1 Power Management

PM APIs can be found in `nwy_pm.h`. They are used to control the module to enter sleep mode or exist from sleep mode, detect the power status of the module, and control the module to shut down quickly or shut down in normal mode.

#### `nwy_pm_state_set`

<b>Function</b>	<code>int nwy_pm_state_set(int mode)</code>
<b>Description</b>	To control the module to enter sleep mode or exist from sleep mode
<b>Parameter</b>	Mode: 0: Wake-up mode 1: Sleep mode
<b>Return value</b>	Successful: <code>NWY_SUCCESS</code> Failed: <code>NWY_ERROR</code>

#### `nwy_power_state`

<b>Function</b>	<code>int nwy_power_state(void)</code>
<b>Description</b>	To detect the power status of the module
<b>Parameter</b>	N/A
<b>Return value</b>	Successful: Power status of the module 1: Normal 2: Abnormal Failed: <code>NWY_ERROR</code>

#### `nwy_power_off`

<b>Function</b>	<code>int nwy_power_off(int option)</code>
<b>Description</b>	To control the module to shut down quickly or shut down in normal mode.

<b>Parameter</b>	option: Modes of shutting down the module 0: quick shutdown 1: shutdown in normal mode
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

### nwy\_set\_pmu\_power\_level

<b>Format</b>	int nwy_set_pmu_power_level(uint32_t id, uint32_t mv)
<b>Description</b>	To select the voltage value of the submodule
<b>Parameter</b>	id: submodule ID mv: range of the voltage (from 1800 to 3000, unit: mV)
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

### nwy\_subpower\_switch

<b>Function</b>	bool nwy_subpower_switch(unsigned int id, bool enabled, bool lp_enabled);
<b>Description</b>	To select the switch of the subpower.
<b>Parameter</b>	id: sub power id enabled: 0-close,1-open at normal run lp_enabled: 0-close,1-open at low power mode
<b>Return value</b>	Failed: 0 Successful: 1

### nwy\_powerkey\_poweroff\_ctrl

<b>Function</b>	int nwy_powerkey_poweroff_ctrl(bool enable);
<b>Description</b>	To enable/disable the shutdown control of the <b>power_n</b> button.
<b>Parameter</b>	enable: Enable/Disable the shutdown control of power_n button. 0: Disable 1: Enable
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

## nwy\_get\_chip\_id

<b>Format</b>	int nwy_get_chip_id( uint8_t *uid)
<b>Description</b>	To obtain the module ID.
<b>Parameter</b>	uid: module ID
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

## nwy\_set\_auto\_poweroff

<b>Function</b>	bool nwy_set_auto_poweroff(uint16_t shut_vol, uint16_t dead_vol, int count, ChargerNoticeCB_t cb)
<b>Description</b>	Automatic shutdown.
<b>Parameter</b>	shut_vol: Shutdown voltage, unit:mV dead_vol: Threshold voltage of module shutdown count: Shutdown voltage alarm times (when the times exceed <b>count</b> under the shutdown voltage, the module shuts down automatically). cb: callback function
<b>Return value</b>	Failed: 0 Successful: 1

## nwy\_set\_back\_light\_level

<b>Format</b>	bool nwy_set_back_light_level(uint32_t back_light, uint32_t level)
<b>Description</b>	To set the backlight brightness.
<b>Parameter</b>	back_light: backlight index (NWY_POWER_RGB_IB0 - NWY_POWER_RGB_IB2) level: Backlight brightness (0 - 63 that is respectively corresponding to 1.68 mA - 54.6mA@3.6V)
<b>Return value</b>	0: failed 1: successful

## nwy\_bootup\_alarm\_set

<b>Format</b>	int nwy_bootup_alarm_set(uint32_t sec_in_day)
<b>Description</b>	To set the bootup alarm clock (daily repeat)
<b>Parameter</b>	sec_in_day: alarm clock time, the number of seconds from 0:0:0
<b>Return value</b>	Successful: NWY_SUCCESS

Failed: NWY_ERROR
-------------------

### nwy\_bootup\_alarm\_del

<b>Format</b>	int nwy_bootup_alarm_del (void)
<b>Description</b>	To delete the bootup alarm clock (daily repeat)
<b>Parameter</b>	NA
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

### nwy\_shutdown\_with\_alarm

<b>Format</b>	int nwy_shutdown_with_alarm(void)
<b>Description</b>	Shutdown with the bootup alarm clock, The RTC device of the alarm clock keeps running in the shutdown mode. Ensure that you have set the bootup alarm clock before invoking this API. Otherwise the invoking is invalid.
<b>Parameter</b>	<b>NA</b>
<b>Return value</b>	Successful:-No value is returned. Failed: NWY_ERROR

## 2.2 I/O Interfaces

### 2.2.1 UART

UART APIs can be found in **nwy\_at\_uart.h**. They are used to configure the UART settings and transmit data through UART.

#### nwy\_uart\_init

<b>Function</b>	int nwy_uart_init(uint32_t name,nwy_uart_mode_t mode);
<b>Description</b>	To initialize UART.
<b>Parameter</b>	name: UART channel
<b>Return value</b>	Successful: hd Failed: -1

## nwy\_uart\_set\_baud

<b>Function</b>	bool nwy_uart_set_baud(uint8_t hd, uint32_t baud);
<b>Description</b>	To set the baud rate of UART
<b>Parameter</b>	hd: Return value of UART init. Baud: baud rate
<b>Return value</b>	N/A

## nwy\_uart\_get\_baud

<b>Function</b>	bool nwy_uart_get_baud(uint8_t hd, uint32_t *baud);
<b>Description</b>	To query the baud rate of UART
<b>Parameter</b>	hd: Return value of UART init. Baud: baud rate
<b>Return value</b>	Failed: 0 Successful: 1

## nwy\_uart\_set\_para

<b>Function</b>	bool nwy_uart_set_para(uint8_t hd, nwy_uart_parity_t parity, nwy_uart_data_bits_t data_size, nwy_uart_stop_bits_t stop_size, bool flowctrl);
<b>Description</b>	To configure UART settings
<b>Parameter</b>	hd: Return value of UART init. parity: parity data_size: data bits stop_size: stop bits flowctrl: flow control
<b>Return value</b>	N/A

## nwy\_uart\_get\_para

<b>Function</b>	bool nwy_uart_get_para(uint8_t hd, nwy_uart_parity_t *parity, nwy_uart_data_bits_t *data_size, nwy_uart_stop_bits_t *stop_size, bool *flowctrl);
<b>Description</b>	To query the current settings of UART
<b>Parameter</b>	hd: Return value of UART init. Parity: parity data_size: data bits stop_size: stop bits

	flowctrl: flow control
<b>Return value</b>	Failed: 0 Successful: 1

### nwy\_uart\_send\_data

<b>Function</b>	int nwy_uart_send_data(uint8_t hd, uint8_t *data_ptr, uint32_t length);
<b>Description</b>	To send data through UART
<b>Parameter</b>	hd: Return value of UART init. data_ptr: data to be sent length: data length
<b>Return value</b>	Successful: number of bytes sent. Failed: 0

### nwy\_uart\_reg\_rcv\_cb

<b>Function</b>	bool nwy_uart_reg_rcv_cb(nwy_uart_rcv_callback_t rcv_cb);
<b>Description</b>	To receive data through UART
<b>Parameter</b>	rcv_cb: callback function of receiving data
<b>Return value</b>	Failed: 0 Successful: 1

### nwy\_uart\_deinit

<b>Function</b>	bool nwy_uart_deinit(uint8_t hd);
<b>Description</b>	To turn off UART.
<b>Parameter</b>	hd: Return value of uart init
<b>Return value</b>	Successful: 1 Failed: 0

## 2.2.2 I2C

I2C APIs can be found in **nwy\_i2c.h**.

### nwy\_i2c\_init

<b>Function</b>	int nwy_i2c_init(const char* i2cDev, unsigned char slaveAddr)
<b>Description</b>	To open an I2C device of the module and set the address of the slave device
<b>Parameter</b>	i2cDev: I2C device name slaveAddr: address of the slave device
<b>Return value</b>	Successful: handles of I2C devices Failed: NWY_ERROR

### nwy\_i2c\_read

<b>Function</b>	int nwy_i2c_read(intfd, unsigned char slaveAddr, unsigned char ofstAddr, unsigned char* ptrBuff, unsigned short length)
<b>Description</b>	To read the data in a specified length from a specified I2C slave device
<b>Parameter</b>	fd: handle of the I2C device slaveAddr: address of the slave device ofstAddr: register address ptrBuff: pointer that points to the buffer that is used to hold data length: Length of data to be read
<b>Return value</b>	Successful: <b>0</b> (no data) or <b>&gt;0</b> (read data) Failed: NWY_ERROR

### nwy\_i2c\_write

<b>Function</b>	int nwy_i2c_write(intfd, unsigned char slaveAddr, unsigned char ofstAddr, unsigned char* ptrData, unsigned short length)
<b>Description</b>	To write the data in a specified length to a specified I2C slave device
<b>Parameter</b>	fd: handle of the I2C device slaveAddr: address of the slave device ofstAddr: register address ptrData: pointer that points to the buffer to be written to length: length of the data to be written
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

## nwy\_i2c\_raw\_get\_byte

<b>Function</b>	int nwy_i2c_raw_get_byte(int fd, uint8_t *data, int start_flag, int stop_flag)
<b>Description</b>	To read the data of I2C device by byte.
<b>Parameter</b>	fd: handle of the I2C device *data: data read start_flag: start flag (only the first byte is set to 1) stop_flag: stop flag (only the last byte is set to 1)
<b>Return value</b>	Successful: NWY_SUCCESS Failed: <0

## nwy\_i2c\_raw\_put\_byte

<b>Function</b>	int nwy_i2c_raw_put_byte(int fd, uint8_t data, int start_flag, int stop_flag)
<b>Description</b>	To write the data of I2C device by byte.
<b>Parameter</b>	fd: handle of the I2C device data: data written start_flag: start flag (only the first byte is set to 1) stop_flag: stop flag (only the last byte is set to 1)
<b>Return value</b>	Successful: NWY_SUCCESS Failed: a value <0

## nwy\_i2c\_deinit

<b>Function</b>	int nwy_i2c_deinit(int fd);
<b>Description</b>	To close the I2C device.
<b>Parameter</b>	fd: handle of the I2C device.
<b>Return value</b>	Successful: NWY_SUCCESS Failed: a value <0



### 2.2.3 SPI

SPI APIs can be found in **nwy\_spi.h**. They are used to initialize the module and transmit data through the SPI bus.

#### nwy\_spi\_init

<b>Function</b>	Int nwy_spi_init(char *spibus, uint8_t mode, uint32_t speed, uint8_t bits)
<b>Description</b>	To enable and configure the SPI bus
<b>Parameter</b>	spibus: name of the SPI bus, "SPI1" and "SPI2" are supported. mode: bus mode, ranging from mode0 to mode3 speed: bus speed rate bits: bits
<b>Return value</b>	Successful: handle of the SPI bus Failed: SPI_EC_ERROR

#### nwy\_spi\_transfer

<b>Function</b>	int nwy_spi_transfer(inthd, uint8_t cs, uint8_t *tx, uint8_t *rx, uint32_t size)
<b>Description</b>	To transmit data through the SPI bus
<b>Parameter</b>	hd: handle of the SPI bus cs: chip selections, cs0 and cs1 are supported. tx: transmit data rx: receive data size: data size
<b>Return value</b>	Successful: SPI_EC_SUCESS Failed: SPI_EC_ERROR

#### nwy\_spi\_deinit

<b>Function</b>	int nwy_spi_deinit(inthd)
<b>Description</b>	To disable the SPI bus
<b>Parameter</b>	hd: handle of the SPI bus
<b>Return value</b>	Successful: SPI_EC_SUCESS Failed: SPI_EC_ERROR

## 2.2.4 GPIO

GPIO APIs can be found in **nwy\_gpio\_open.h**. They are used to set the GPIO to input, output or interrupt mode. GPIO 0,2, and 3 are the default GPIO port. You can also configure the GPIO port as required. For the custom GPIO configuration, contact Neoway FAE.

### nwy\_gpio\_get\_direction

<b>Function</b>	int nwy_gpio_get_direction(uint32 gpio_id)
<b>Description</b>	To obtain the GPIO direction
<b>Parameter</b>	gpio_id: GPIO ID
<b>Return value</b>	gpio direction

### nwy\_gpio\_get\_value

<b>Function</b>	int nwy_gpio_get_value(uint32 gpio_id)
<b>Description</b>	To obtain the level state of the GPIO pin.
<b>Parameter</b>	gpio_id: GPIO ID
<b>Return value</b>	GPIO pin

### nwy\_gpio\_set\_direction

<b>Function</b>	int nwy_gpio_set_direction(uint32 gpio_id, wy_dir_mode_t direct)
<b>Description</b>	To configure the GPIO direction
<b>Parameter</b>	gpio_id: GPIO ID direct: GPIO direction
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

### nwy\_gpio\_set\_value

<b>Function</b>	int nwy_gpio_set_value(uint32 gpio_id, nwy_value_t value)
<b>Description</b>	To configure the level state of the GPIO pin.
<b>Parameter</b>	gpio_id: GPIO ID value: nwy_value_t
<b>Return value</b>	Successful: NWY_SUCCESS

Failed: NWY_ERROR
-------------------

### nwy\_open\_gpio\_irq\_config

<b>Function</b>	int nwy_open_gpio_irq_config(uint32_t gpio_id, uint8_t irq_mode, nwy_irq_callbackcb);
<b>Description</b>	To set the interrupt mode of a GPIO
<b>Parameter</b>	gpio_id: GPIO ID irq_mode: GPIO interrupt mode cb: nwy_irq_callback
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

### nwy\_gpio\_pullup\_or\_pulldown

<b>Function</b>	int nwy_gpio_pullup_or_pulldown(uint32_t gpio_id, int pull);
<b>Description</b>	To set pull-up/pull-down of GPIO.
<b>Parameter</b>	gpio_id:GPIO ID pull: 0 - pull down 1 - pull up
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

### nwy\_gpio\_open\_irq\_enable

<b>Function</b>	int nwy_gpio_open_irq_enable(uint32_t gpio_id);
<b>Description</b>	To enable GPIO interrupt.
<b>Parameter</b>	gpio_id: GPIO ID
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

### nwy\_gpio\_open\_irq\_disable

<b>Function</b>	int nwy_gpio_open_irq_disable(uint32_t gpio_id);
<b>Description</b>	To disable GPIO interrupt.
<b>Parameter</b>	gpio_id: GPIO ID
<b>Return value</b>	Successful: NWY_SUCCESS

Failed: NWY_ERROR
-------------------

## nwy\_close\_gpio

<b>Function</b>	int nwy_close_gpio(uint32_t gpio_id);
<b>Description</b>	To disable GPIO.
<b>Parameter</b>	gpio_id: GPIO ID
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

## 2.2.5 ADC

ADC API can be found in `nwy_adc.h`. It is used to collect voltage values through the ADC port.

### nwy\_adc\_get

<b>Function</b>	int nwy_adc_get(nwy_adc_t channel, nwy_adc_aux_scale_t scale);
<b>Description</b>	To get ADC value.
<b>Parameter</b>	channel: ADC channel scale: voltage range
<b>Return value</b>	Voltage value obtained. (unit:mV)

## 2.3 Peripherals

### 2.3.1 Audio

Audio APIs can be found in `nwy_audio_api.h`.

#### nwy\_audio\_pa\_control

<b>Function</b>	int nwy_audio_pa_control(nwy_pa_type pa_type, int gpio_num, nwy_pa_mode mode)
<b>Description</b>	To select the type of the external audio amplifier.
<b>Parameter</b>	pa_type: audio amplifier type gpio_num: the GPIO that is connected to the amplifier switch.

	mode: gain selection (valid for the specific power amplifier)
<b>Return value</b>	Successful: NWY_SUCESS Failed: others

### nwy\_audio\_player\_open

<b>Function</b>	int nwy_audio_player_open(player_event_handler handler)
<b>Description</b>	To initialize the audio player
<b>Parameter</b>	handler: callback function that indicates the audio has finished playing.
<b>Return value</b>	Successful: NWY_SUCESS Failed: other values

### nwy\_audio\_player\_stop

<b>Function</b>	int nwy_audio_player_stop(void)
<b>Description</b>	To stop playing audio
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: NWY_SUCESS Failed: other values

### nwy\_audio\_player\_close

<b>Function</b>	void nwy_audio_player_close(void)
<b>Description</b>	To close the audio player.
<b>Parameter</b>	N/A.
<b>Return value</b>	void

### nwy\_audio\_player\_play

<b>Function</b>	int nwy_audio_player_play (uint8_t *pdata, uint32_t len)
<b>Description</b>	To play buffer data
<b>Parameter</b>	pdata: PCM data len: data length
<b>Return value</b>	Successful: NWY_SUCESS Failed: other values

## nwy\_audio\_set\_handset\_vol

<b>Function</b>	void nwy_audio_set_handset_vol(constint step)
<b>Description</b>	To set the volume level for the speaker
<b>Parameter</b>	Step: volume level, ranging from 0 to 100
<b>Return value</b>	void

## nwy\_audio\_get\_handset\_vol

<b>Function</b>	unsigned int nwy_audio_get_handset_vol(void)
<b>Description</b>	To get the speaker volume level.
<b>Parameter</b>	Void
<b>Return value</b>	0-100

## nwy\_audio\_set\_mic\_vol

<b>Function</b>	void nwy_audio_set_mic_vol(const int step)
<b>Description</b>	To set the mic volume.
<b>Parameter</b>	step: volume level, ranging from 0 to 100.
<b>Return value</b>	void

## nwy\_audio\_get\_mic\_vol

<b>Function</b>	unsigned int nwy_audio_get_mic_vol(void)
<b>Description</b>	To query the mic volume level.
<b>Parameter</b>	void
<b>Return value</b>	0-100

## nwy\_audio\_recorder\_open

<b>Function</b>	int nwy_audio_recorder_open(record_event_handler handler)
<b>Description</b>	To initialize the recording.
<b>Parameter</b>	record_event_handler handler: callback function of the recording.
<b>Return value</b>	Successful: NWY_SUCCESS Failed: others

## nwy\_audio\_recorder\_start

<b>Function</b>	int nwy_audio_recorder_start(void)
<b>Description</b>	To start recording.
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: NWY_SUCESS Failed: others

## nwy\_audio\_recorder\_stop

<b>Function</b>	int nwy_audio_recorder_stop(void)
<b>Description</b>	To stop recording.
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: NWY_SUCESS Failed: others

## nwy\_audio\_recorder\_close

<b>Function</b>	void nwy_audio_recorder_close(void)
<b>Description</b>	To close recording.
<b>Parameter</b>	void
<b>Return value</b>	void

## nwy\_tts\_playbuf

<b>Function</b>	int nwy_tts_playbuf(char * data, int size, nwy_tts_encode_t type, tts_cb cb, void* cb_param)
<b>Description</b>	To play TTS.
<b>Parameter</b>	data: TTS data pointer. size: TTS data length. type: TTS encoding type. cb: callback of the play complete status. cb_param: callback interface parameter.
<b>Return value</b>	Successful: NWY_SUCESS Failed: others

## nwy\_tts\_stop\_play

<b>Function</b>	void nwy_tts_stop_play(void)
<b>Description</b>	To stop TTS playing.
<b>Parameter</b>	void
<b>Return value</b>	void

## nwy\_audio\_tone\_play

<b>Function</b>	void nwy_audio_tone_play(const char * tone, unsigned time, int vol)
<b>Description</b>	To play tone audio.
<b>Parameter</b>	Tone:dtmf Time: duration time (unit:ms) vol: volume, ranging from 0 to 15.
<b>Return value</b>	void

## 2.3.2 LED

LED APIs can be found in **nwy\_led.h**.

## nwy\_led\_back\_light\_open

<b>Function</b>	int nwy_led_back_light_open(int mode);
<b>Description</b>	To enable LED backlight
<b>Parameter</b>	Mode: LED channel to turn on backlight.
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR

## nwy\_led\_back\_light\_close

<b>Function</b>	int nwy_led_back_light_close(int mode);
<b>Description</b>	To turn off LED backlight
<b>Parameter</b>	mode: LED channel to turn off backlight.
<b>Return value</b>	Successful: NWY_SUCCESS Failed: NWY_ERROR



### 2.3.3 Keypad

Keypad API can be found in **nwy\_keypad.h**.

#### reg\_nwy\_key\_cb

<b>Function</b>	void reg_nwy_key_cb(nwy_key_event_cb_tcb);
<b>Description</b>	To register a callback function of the keypad event
<b>Parameter</b>	cb:typedef void (*nwy_key_event_cb_t)(nwy_key_t key, nwy_keyState_tevt);
<b>Return value</b>	N/A.

#### nwy\_keypad\_debounce\_time

<b>Format</b>	void nwy_keypad_debounce_time(uint32_t debunc,uint32_t itv)
<b>Description</b>	To set the keypad debounce time.
<b>Parameter</b>	debunc: debounce time (ms) Itv: debounce time (ms)
<b>Return value</b>	N/A.

### 2.3.4 LCD

LCD APIs can be found in **nwy\_lcd\_bus.h**.

#### nwy\_lcd\_bus\_init

<b>Function</b>	void nwy_lcd_bus_init(nwy_lcd_bus_config_t *lcd_bus_config);
<b>Description</b>	To initialize the LCD driver.
<b>Parameter</b>	nwy_lcd_bus_config_t *lcd_bus_config: configuration information of GOUDA LCD interface.
<b>Return value</b>	N/A.

#### nwy\_lcd\_bus\_write\_cmd

<b>Function</b>	bool nwy_lcd_bus_write_cmd(unsignedchar cmd);
<b>Description</b>	Write a command to the LCD

<b>Parameter</b>	cmd:addr Command to write
<b>Return value</b>	Successful: true Failed: false

### nwy\_lcd\_bus\_write\_data

<b>Function</b>	bool nwy_lcd_bus_write_data(unsigned char data);
<b>Description</b>	To write a data to the LCD.
<b>Parameter</b>	data: which data you want to write
<b>Return value</b>	Successful: true Failed: false

### nwy\_lcd\_bus\_write\_datas

<b>Function</b>	unsigned int nwy_lcd_bus_write_datas(void *data, unsigned int size);
<b>Description</b>	To write data to the LCD.
<b>Parameter</b>	*data: datas you want to write    size:data size
<b>Return value</b>	Data size

### nwy\_lcd\_bus\_deinit

<b>Function</b>	void nwy_lcd_bus_deinit(void);
<b>Description</b>	To disable the LCD driver.
<b>Parameter</b>	void
<b>Return value</b>	void

## 2.3.5 SD

SD APIs can be found in **nwy\_file.h**.

### nwy\_sdk\_sdcard\_mount

<b>Function</b>	bool nwy_sdk_sdcard_mount(void)
<b>Description</b>	To mount the SD card.

<b>Parameter</b>	void
<b>Return value</b>	Successful: true Failed: false

### nwy\_sdk\_sdcard\_unmount

<b>Function</b>	void nwy_sdk_sdcard_unmount(void)
<b>Description</b>	To unmount the SD card.
<b>Parameter</b>	void
<b>Return value</b>	void

### nwy\_read\_sdcard\_status

<b>Function</b>	int nwy_read_sdcard_status(void)
<b>Description</b>	To read the SD card status.
<b>Parameter</b>	void
<b>Return value</b>	1: mount status 0: unmount status

## 2.3.6 Spi flash

The definitions of these API functions can be found in **nwy\_spi.h**.

### nwy\_vfs\_block\_device\_create

<b>Format</b>	nwy_block_device_t *nwy_vfs_block_device_create(nwy_spi_flash_t *dev)
<b>Description</b>	To create the logical block device.
<b>Parameter</b>	dev: SPI flash information. Currently only the block size and the number of blocks are used, other parameters are omitted.
<b>Return value</b>	The logical block device.

### nwy\_vfs\_mount

<b>Format</b>	int nwy_vfs_mount(const char *base_path, nwy_block_device_t *nwy_bdev)
<b>Description</b>	To mount the block device to the file system.

<b>Parameter</b>	base_path: mount point of this block device in the file system. nwy_bdev: logical block device
<b>Return value</b>	-1: failed 0: successful

## nwy\_read\_sdcard\_status

<b>Format</b>	int nwy_vfs_mkfs(nwy_block_device_t *nwy_bdev)
<b>Description</b>	To format the block device.
<b>Parameter</b>	nwy_bdev: logical block device
<b>Return value</b>	-1: failed 0: successful

## 2.4 Services

### 2.4.1 Data

Data APIs can be found in **nwy\_data.h**. They are used to establish or close a dial-up connection, configure the dial-up settings and obtain the dial-up status and information related to dialing.

#### nwy\_data\_get\_srv\_handle

<b>Function</b>	int nwy_data_get_srv_handle(nwy_data_cb_func cb_func)
<b>Description</b>	To obtain the resource handle of a dial-up connection and configure the callback function The handle is used to operate the connection. The callback function is used to report the status change of the connection.
<b>Parameter</b>	cb_func: registered callback function, used to report status change of the connection
<b>Return value</b>	Successful: obtained resource handle, a positive integer number Failed: error codes

#### nwy\_data\_release\_srv\_handle

<b>Function</b>	void nwy_data_release_srv_handle(int hndl)
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<b>Description</b>	To release the resource handle of a specified dial-up connection and to unregister the callback function. The dial-up connection will be closed if it is valid before unregistering the callback function.
<b>Parameter</b>	hndl: resource handle of a dial-up connection. It is obtained by calling <code>nwy_data_get_srv_handle()</code> .
<b>Return value</b>	N/A.

### nwy\_data\_start\_call

<b>Function</b>	<code>int nwy_data_start_call(inthndl, nwy_data_start_call_v02_t *param)</code>
<b>Description</b>	To establish a specified dial-up connection This API function is asynchronous. The dialup result is obtained by calling the callback function to which <b>nwy_data_get_srv_handle()</b> registers.
<b>Parameter</b>	hndl: a specified resource handle, obtained by calling <code>nwy_data_get_srv_handle()</code> . para: a dialup parameter
<b>Return value</b>	Successful: 0 Failed: a value <0

### nwy\_data\_stop\_call

<b>Function</b>	<code>int nwy_data_stop_call(inthndl)</code>
<b>Description</b>	To close a specified dial-up connection This API function is asynchronous. The result is obtained by calling the callback function to which <code>nwy_data_get_srv_handle()</code> registers.
<b>Parameter</b>	hndl: specified resource handle, obtained by calling <code>nwy_data_get_srv_handle()</code> .
<b>Return value</b>	Successful: 0 Failed: a value <0

### nwy\_data\_get\_ip\_addr

<b>Function</b>	<code>int nwy_data_get_ip_addr(inthndl, nwy_data_addr_t_info * info_ptr, int *len)</code>
<b>Description</b>	To obtain the IP address of a dial-up connection This function is called only after a dialup connection is established successfully.
<b>Parameter</b>	hndl: a specified resource handle, obtained by calling <code>nwy_data_get_srv_handle()</code> . info_ptr: structure or structure array that is used to return the address information. Ensure that the structure array is large enough when the dialup connection obtains multiple addresses. For details, see the structure definitions in

	<b>nwy_data_addr_t_info.</b> len: quantity of obtained addresses
<b>Return value</b>	Successful: 0 Failed: a value <0

## nwy\_data\_set\_profile

<b>Function</b>	int nwy_data_set_profile(intprofile_idx, nwy_data_profile_type_tprofile_type, nwy_data_profile_info_t *profile_info);
<b>Description</b>	To specify a profile ID and type and to modify the parameters of the profile.
<b>Parameter</b>	profile_idx: ID of the profile to be modified. profile_type: type of profile to be modified. profile_info: modified parameters of the profile, including PDP type, APN, authentication method, user name, and password. For details, see nwy_data_profile_info_t.
<b>Return value</b>	Successful: 0 Failed: a value <0

## nwy\_data\_get\_profile

<b>Function</b>	int nwy_data_get_profile(intprofile_idx, nwy_data_profile_type_tprofile_type, nwy_data_profile_info_t *profile_info);
<b>Description</b>	To obtain the current parameters of the specified profile with a specified ID and type.
<b>Parameter</b>	profile_idx: profile ID to be obtained profile_type: profile type to be obtained profile_info: returned profile information
<b>Return value</b>	Successful: 0 Failed: a value <0

## nwy\_ip4addr\_ntoa

<b>Function</b>	char* nwy_ip4addr_ntoa(const nwy_ip4_addr_t *addr)
<b>Description</b>	To convert the format of the IPv4 address.
<b>Parameter</b>	addr: IPv4 address
<b>Return value</b>	IPv4 address

## nwy\_ip6addr\_ntoa

<b>Function</b>	char *nwy_ip6addr_ntoa(const nwy_ip6_addr_t *addr)
<b>Description</b>	To convert the format of the IPv6 address.
<b>Parameter</b>	addr: IPv6 address
<b>Return value</b>	IPv6 address

## 2.4.2 Voice

Voice APIs can be found in **nwy\_voice.h**.

## nwy\_voice\_call\_start

<b>Function</b>	int nwy_voice_call_start(uint8_t sim_id, char *phone_num)
<b>Description</b>	To make a call
<b>Parameter</b>	sim_id: only SIM 1 is supported currently. phone_num: destination phone number
<b>Return value</b>	Successful: NWY_RES_OK Failed: nwy_error_t

## nwy\_voice\_call\_end

<b>Function</b>	int nwy_voice_call_end(uint8_t sim_id)
<b>Description</b>	To hang up a call
<b>Parameter</b>	sim_id: only SIM 1 is supported currently.
<b>Return value</b>	Successful: NWY_RES_OK Failed: nwy_error_t

## nwy\_voice\_call\_autoanswer

<b>Function</b>	int nwy_voice_call_autoanswer()
<b>Description</b>	To answer a call
<b>Parameter</b>	None
<b>Return value</b>	Successful: NWY_RES_OK Failed: nwy_error_t

## nwy\_voice\_call\_hold

<b>Function</b>	int nwy_voice_call_hold(uint8_t sim_id)
<b>Description</b>	To hold an incoming call
<b>Parameter</b>	sim_id: only SIM 1 is supported currently.
<b>Return value</b>	Successful: NWY_RES_OK Failed: nwy_error_t

## nwy\_voice\_call\_unhold

<b>Function</b>	int nwy_voice_call_unhold(uint8_t sim_id)
<b>Description</b>	To answer a call from a hold-on state
<b>Parameter</b>	sim_id: only SIM 1 is supported currently.
<b>Return value</b>	Successful: NWY_RES_OK Failed: other values

## nwy\_voice\_setvolte

<b>Function</b>	int nwy_voice_setvolte(uint8_t sim_id, uint8_t setvolte)
<b>Description</b>	To configure VoLTE
<b>Parameter</b>	sim_id: only SIM 1 is supported currently. setvolte: used to enable IMS
<b>Return value</b>	Successful: NWY_RES_OK Failed: other values

## nwy\_get\_voice\_callerid

<b>Function</b>	void nwy_get_voice_callerid(char* nwy_call_rsp)
<b>Description</b>	To get the called phone information.
<b>Parameter</b>	nwy_call_state: called phone information.
<b>Return value</b>	void



## nwy\_get\_voice\_state

<b>Function</b>	void nwy_get_voice_state(char* nwy_call_state)
<b>Description</b>	To get the called status.
<b>Parameter</b>	nwy_call_rsp: called status
<b>Return value</b>	void

## 2.4.3 SIM

SIM APIs can be found in **sim.h**. They are used to obtain SIM card information and configure card status.

## nwy\_sim\_get\_card\_status

<b>Function</b>	nwy_sim_status nwy_sim_get_card_status()
<b>Description</b>	To obtain the SIM card status
<b>Parameter</b>	N/A.
<b>Return value</b>	The SIM card is ready: <b>NWY_SIM_STATUS_READY</b> The SIM card is not inserted: <b>NWY_SIM_STATUS_NOT_INSERT</b> The SIM card is locked by PIN: <b>NWY_SIM_STATUS_PIN1</b> The SIM card is locked by PUK: <b>NWY_SIM_STATUS_PUK1</b> The SIM card is busy: <b>NWY_SIM_STATUS_BUSY</b>

## nwy\_sim\_get\_iccid

<b>Function</b>	nwy_result_type nwy_sim_get_iccid(nwy_sim_result_type *iccid_buf)
<b>Description</b>	To obtain ICCID of the SIM card
<b>Parameter</b>	iccid_buf: ICCID of the memory card
<b>Return value</b>	Successful: <b>NWY_RES_OK</b> Failed: <b>NWY_RES_ERROR</b>

## nwy\_sim\_get\_imsi

<b>Function</b>	nwy_result_type nwy_sim_get_imsi(nwy_sim_result_type *imsi_buf)
<b>Description</b>	To obtain IMSI of the SIM card
<b>Parameter</b>	imsi_buf: IMSI of the memory card

<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR
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### nwy\_sim\_enable\_pin

<b>Function</b>	nwy_result_type nwy_sim_enable_pin(nwy_sim_result_type *sim_lock)
<b>Description</b>	To enable PIN of the SIM card
<b>Parameter</b>	sim_lock: PIN code of the SIM card.
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

### nwy\_sim\_disable\_pin

<b>Function</b>	nwy_result_type nwy_sim_disable_pin(nwy_sim_result_type *sim_unlock)
<b>Description</b>	To disable PIN of the SIM card
<b>Parameter</b>	sim_unlock: PIN code of the SIM card.
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

### nwy\_sim\_get\_pin\_mode

<b>Function</b>	nwy_result_type nwy_sim_get_pin_mode(nwy_sim_result_type *pin_mode)
<b>Description</b>	To obtain the PIN status of the SIM card
<b>Parameter</b>	pin_mode: PIN status of the SIM card. For details, see the definitions in <b>sim.h</b> .
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

### nwy\_sim\_get\_imei

<b>Function</b>	nwy_result_type nwy_result_type nwy_sim_get_imei(nwy_sim_result_type *imei)
<b>Description</b>	To obtain the IMEI number of the device.
<b>Parameter</b>	Device's IMEI number
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

## nwy\_sim\_set\_simid

<b>Function</b>	nwy_result_type nwy_sim_set_simid(uint8 nSwitchSimID);
<b>Description</b>	To switch SIM cards.
<b>Parameter</b>	nSwitchSimIDs: SIM card ID, ranging from 0 to 1.
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

## nwy\_sim\_get\_simid

<b>Function</b>	uint8 nwy_sim_get_simid()
<b>Description</b>	To get the current SIM card ID.
<b>Parameter</b>	void
<b>Return value</b>	SIM card ID

## nwy\_sim\_get\_msisdn

<b>Format</b>	int nwy_sim_get_msisdn(nwy_sim_id_t sim_id, char* msisdn_buf, size_t buf_len)
<b>Description</b>	To obtain MSISDN of the SIM card.
<b>Parameter</b>	sim_id: ID of the SIM card slot, for details, see nwy_sim.h. msisdn_buf: MSISDN value buf_len: invalid currently
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

## nwy\_sim\_csim

<b>Format</b>	int nwy_sim_csim(nwy_sim_id_t sim_id, char *indata, int indata_len, char *outdata, int outdata_len)
<b>Description</b>	To send the APDU command to the SIM card.
<b>Parameter</b>	nwy_sim_id_t sim_id: SIMID the is operated. char *indata: APDU command that is inputted. int indata_len: length of the APDU command that is inputted. char *outdata: buffer that holds the result of the command. int outdata_len: length of the buffer that holds the result of the command.
	Confirm the SIMID of the current operation before executing the command. If it does not match the actual situation, you need to call the nwy_sim_set_simid interface to

	switch. After the switch is successful, the module needs to restart.
<b>Return value</b>	-1: fail to execute the command. A positive number: indicates the command length that is outputted.

### nwy\_sim\_verify\_pin

<b>Format</b>	int nwy_sim_verify_pin(nwy_sim_id_t sim_id, const char* pin)
<b>Description</b>	To verify the PIN code of the SIM card.
<b>Parameter</b>	sim_id: ID of the SIM card slot, for details, see nwy_sim.h. pin: PIN of the SIM card.
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

### nwy\_sim\_unblock

<b>Format</b>	int nwy_sim_unblock(nwy_sim_id_t sim_id, const char* puk, const char* new_pin)
<b>Description</b>	To input the PUK code. After the SIM card is locked by a PIN, you can invoke this API to enter the PUK to unlock the SIM card.
<b>Parameter</b>	sim_id: ID of the SIM card slot, for details, see nwy_sim.h. puk: PUK of the SIM card. pin: PIN of the SIM card.
<b>Return value</b>	Successful: NWY_RES_OK Failed: NWY_RES_ERROR

### nwy\_sim\_get\_lacid

<b>Format</b>	int nwy_sim_get_lacid(int *lac, int *cid)
<b>Description</b>	To obtain the LAC and CID value.
<b>Parameter</b>	Lac: location area code, cell code cid: cell ID.
<b>Return value</b>	Successful: NWY_SUCESS Failed: NWY_GEN_E_UNKNOWN

## 2.4.4 USSD

The definitions of these API function can be found in `nwy_usd.h`, used to realize the function of sending USSD, and so on.

### `nwy_usd_send_msg`

<b>Format</b>	<code>int nwy_usd_send_msg(uint8 simid, char* ussd_string, uint8 dcs, nwy_usd_info_t* ussd_info)</code>
<b>Description</b>	To sen USSD and obtain the Return value.
<b>Parameter</b>	<p><code>sim_id</code>: ID of the SIM card slot.</p> <p><code>ussd_string</code>: Character string of the USSD command.</p> <p><code>dcs</code>: coding method, 0 by default.</p> <p><code>ussd_info</code>: Return value of USSD.</p>
<b>Return value</b>	<p>Successful: <code>NWY_USSD_SUCCESS</code></p> <p>Failed: <code>NWY_USSD_ERROR</code></p>

## 2.4.5 SMS

SMS APIs can be found in `nwy_sms.h`. They are used to receive and send SMS messages as well as set their storage location.

### `nwy_init_sms_option`

<b>Function</b>	<code>nwy_result_t nwy_init_sms_option()</code>
<b>Description</b>	To initialize the parameters of the SMS service
<b>Parameter</b>	N/A.
<b>Return value</b>	<p>Successful: <code>NWY_SMS_SUCCESS</code></p> <p>Failed: <code>NWY_SMS_ERROR</code></p>

### `nwy_sms_set_storage`

<b>Function</b>	<code>nwy_result_t nwy_sms_set_storage(nwy_sms_storage_type_e sms_storage)</code>
<b>Description</b>	To set the storage location of SMS messages
<b>Parameter</b>	<code>nwy_sms_storage_type_e sms_storage</code> : for details, see <code>nwy_sms.h</code>
<b>Return value</b>	<p>Successful: <code>NWY_SMS_SUCCESS</code></p> <p>Failed: <code>NWY_SMS_ERROR</code></p>

## nwy\_sms\_get\_storage

<b>Function</b>	nwy_sms_storage_type_e nwy_sms_storage_type_e nwy_sms_get_storage()
<b>Description</b>	To obtain the storage location of SMS messages
<b>Parameter</b>	N/A.
<b>Return value</b>	nwy_sms_storage_type_e type of the storage location of the SMS messages, for details, see <b>nwy_sms.h</b> .

## nwy\_set\_report\_option

<b>Function</b>	nwy_result_t nwy_result_t nwy_set_report_option(uint8_t mode, uint8_t mt, uint8_t bm, uint8_t ds, uint8_t bfr)
<b>Description</b>	To set the report mode of SMS messages
<b>Parameter</b>	uint8_t mode uint8_t mt uint8_t bm uint8_t ds uint8_t bfr For details, see the definition of AT+CNMI in the AT Commands Manual.
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

## nwy\_sms\_set\_sca

<b>Function</b>	nwy_result_t nwy_sms_set_sca(char *sca, unsigned tosca)
<b>Description</b>	To set the number for a SMS center
<b>Parameter</b>	char *sca unsigned tosca For details, see the definition of AT+CSCA in AT Commands Manual
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

## nwy\_sms\_get\_sca

<b>Function</b>	nwy_result_t nwy_sms_get_sca(nwy_sms_result_type *sca)
<b>Description</b>	To obtain the SMSC number
<b>Parameter</b>	nwy_sms_result_type *sca For details, see <b>nwy_sms.h</b> .
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

### nwy\_sms\_send\_message

<b>Function</b>	nwy_result_t nwy_sms_send_message(nwy_sms_info_type_t *p_sms_data)
<b>Description</b>	To send an SMS message
<b>Parameter</b>	nwy_sms_info_type_t *p_sms_data For details, see <b>nwy_sms.h</b>
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

### nwy\_sms\_rcv\_message

<b>Function</b>	void nwy_sms_rcv_message(nwy_sms_rcv_info_type_t *sms_data)
<b>Description</b>	To receive an SMS message
<b>Parameter</b>	nwy_sms_rcv_info_type_t *sms_data For details, see <b>nwy_sms.h</b>
<b>Return value</b>	N/A

### nwy\_sms\_delete\_message

<b>Function</b>	nwy_result_t nwy_sms_delete_message(uint16_t nindex, nwy_sms_storage_type_e nStorage)
<b>Description</b>	To delete an SMS message
<b>Parameter</b>	uint16_t nindex nwy_sms_storage_type_e nStorage For details, see <b>nwy_sms.h</b> .
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

### nwy\_sms\_read\_message

<b>Function</b>	nwy_result_t nwy_sms_read_message(unsigned nindex, nwy_sms_rcv_info_type_t *sms_data);
<b>Description</b>	To read an SMS message
<b>Parameter</b>	unsigned nindex nwy_sms_rcv_info_type_t *sms_data For details, see <b>nwy_sms.h</b>
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

## nwy\_sms\_send\_pdu\_message

<b>Function</b>	nwy_result_t nwy_sms_send_pdu_message(char *data, int data_len);
<b>Description</b>	To send a PDU SMS message.
<b>Parameter</b>	*data: PDU data data_len: PDU data length, see nwy_sms.h.
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

## nwy\_sms\_delete\_message\_by\_type

<b>Format</b>	nwy_result_t nwy_sms_delete_message_by_type(nwy_sms_msg_dflag_e delflag, nwy_sms_storage_type_e nStorage)
<b>Description</b>	To delete one type of SMS message.
<b>Parameter</b>	nwy_sms_msg_dflag_e delflag nwy_sms_storage_type_e nStorage, for detail, see nwy_sms.h.
<b>Return value</b>	Successful: NWY_SMS_SUCCESS Failed: NWY_SMS_ERROR

## 2.4.6 Location

Location APIs can be found in **nwy\_loc.h**. They are used to enable the positioning function and configure the positioning parameters.

## nwy\_loc\_start\_navigation

<b>Function</b>	int nwy_loc_start_navigation()
<b>Description</b>	To enable the positioning function
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: true Failed: false

## nwy\_loc\_stop\_navigation

<b>Function</b>	int nwy_loc_stop_navigation()
<b>Description</b>	To disable the positioning function



<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: true Failed: false

### nwy\_loc\_set\_position\_mode

<b>Function</b>	int nwy_loc_set_position_mode(nwy_loc_position_mode_t pos_mode)
<b>Description</b>	To set the position mode
<b>Parameter</b>	mode: the position mode, for details, see the definitions in <b>nwy_loc.h</b> .
<b>Return value</b>	Successful: true Failed: false

### nwy\_loc\_set\_startup\_mode

<b>Function</b>	int nwy_loc_set_startup_mode(nwy_loc_startup_mode startup)
<b>Description</b>	To set the startup mode
<b>Parameter</b>	startup: startup mode. For details, see <b>nwy_loc.h</b> .
<b>Return value</b>	Successful: true Failed: false

### nwy\_loc\_nmea\_format\_mode

<b>Function</b>	int nwy_loc_nmea_format_mode(uint16 cmd, int16 sel_parameter)
<b>Description</b>	To set the report frequency and fields of NMEA data
<b>Parameter</b>	cmd: select the report frequency or the report field, corresponding to the value of <b>sel_parameter</b> . For details, see the datasheet of the external chip, for example, <i>CASIC Multi-mode Satellite Navigation Receiver Protocol Specifications</i> of Zhongke Microelectronics.
<b>Return value</b>	Successful: true Failed: false

### nwy\_loc\_get\_nmea\_data

<b>Function</b>	void nwy_loc_get_nmea_data(char* data)
<b>Description</b>	To obtain NMEA data actively
<b>Parameter</b>	data: NMEA data to be read

<b>Return value</b>	N/A.
---------------------	------

### nwy\_loc\_set\_server

<b>Function</b>	int nwy_loc_set_server(char *str_url,intport,char *user,char *password)
<b>Description</b>	To configure the AGNSS server
<b>Parameter</b>	str_url: domain name of the AGNSS server port: port number user: user name password: password
<b>Return value</b>	Successful: true Failed: false

### nwy\_loc\_cipgsmloc\_open

<b>Function</b>	bool nwy_loc_cipgsmloc_open (bool value,nwy_loc_cipgsmloc_callback cb)
<b>Description</b>	To open LBS positioning.
<b>Parameter</b>	value: open or close LBS positioning. Callback function definition typedef struct { double lat; //latitude double lng; //longitude double alt; //degree of accuracy }nwy_cipgsmloc_info_t;  typedef struct { char result; //0 == nwy_cipgsmloc_info_t 1 == errmsg union { nwy_cipgsmloc_info_t data; char errmsg[48]; }info; }nwy_log_cipgsmloc_result_t; typedef void (*nwy_loc_cipgsmloc_callback)(nwy_log_cipgsmloc_result_t *text); nwy_loc_cipgsmloc_callback cb // the callback function that informs the latitude and longitude of upper layer.
<b>Return value</b>	Successful: true Failed: false

## nwy\_loc\_agps\_open

<b>Function</b>	bool nwy_loc_agps_open(bool value)
<b>Description</b>	To enable the A-GPS function
<b>Parameter</b>	value: enabling or disabling the A-GPS function
<b>Return value</b>	Successful: true Failed: false

## nwy\_lbs\_get\_info

<b>Function</b>	int nwy_lbs_get_info(char *strimei, nwy_lbs_plmn_info *pPlmn, int *strRssi)
<b>Description</b>	To obtain the LBS information.
<b>Parameter</b>	strimei: IMEI number pPlmn: plmn information strRssi: signal value
<b>Return value</b>	Successful: true Failed: false

## 2.4.7 Wi-Fi Scanning

Wi-Fi scanning APIs can be found in **nwy\_wifi.h**. It is used to scan Wi-Fi hotspots

## nwy\_wifi\_scan

<b>Function</b>	Int nwy_wifi_scan(nwy_wifi_scan_list_t *scan_list)
<b>Description</b>	To scan and list Wi-Fi hotspots
<b>Parameter</b>	scan_list: Wi-Fi hotspot list
<b>Return value</b>	Fail to start the device: NWY_WIFI_OPEN_FAILED No Wi-Fi hotspot is found: NWY_WIFI_SCAN_FAILED 0: a Wi-Fi hotspot is scanned successfully

## 2.4.8 Network

Network APIs can be found in **nwy\_network.h**. They are used to query and set networks registration and network modes. These functions can be used to register callback function for network status monitoring.

## nwy\_nw\_get\_register\_info

<b>Function</b>	int nwy_nw_get_register_info(nwy_nw_regs_info_type_t *p_regs_info)
<b>Description</b>	To obtain the current network registration information
<b>Parameter</b>	p_regs_info: network registration information. It is an output parameter. For details, see <b>nwy_network.h</b> .
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_get\_network\_mode

<b>Function</b>	int nwy_nw_get_network_mode(nwy_nw_mode_type_t *p_mode)
<b>Description</b>	To obtain the current network mode
<b>Parameter</b>	p_mode: network mode. It is an output parameter. For details, see the definitions in <b>nwy_network.h</b> .
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_set\_network\_mode

<b>Function</b>	int nwy_nw_set_network_mode(nwy_nw_mode_type_t mode)
<b>Description</b>	To set the current network mode
<b>Parameter</b>	mode: network mode. For details, see <b>nwy_network.h</b> .
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_get\_operator\_name

<b>Function</b>	int nwy_nw_get_operator_N/Ame (nwy_nw_operator_name_t *opt_name)
<b>Description</b>	To obtain the operator of the network that the module registers to, including Long EONS (Enhanced Operator name String), Short EONS, MCC and MNC. For details, see the definition of nwy_nw_operator_name_t.
<b>Parameter</b>	opt_name: operator name that is returned. It is an output parameter.
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_get\_signal\_csq

<b>Function</b>	int nwy_nw_get_signal_csq(int *csq_val)
<b>Description</b>	To obtain the CSQ of the current network
<b>Parameter</b>	csq_val: CSQ of the current network. It is an output parameter. Its value is the same with the value of CSQ that is queried by the AT command.
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_register\_callback\_fnuc

<b>Function</b>	int nwy_nw_register_callback_fnuc( nwy_nw_cb_funccb)
<b>Description</b>	To register a network callback function that is customized
<b>Parameter</b>	cb: network callback function
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_unregister\_callback\_fnuc

<b>Function</b>	int nwy_nw_unregister_callback_fnuc()
<b>Description</b>	To unregister a network callback function that is customized
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_cb\_func

<b>Function</b>	void nwy_cb_func(nwy_nw_regs_ind_type_tind_type, void *ind_struct)
<b>Description</b>	To set the type of a custom callback function
<b>Parameter</b>	ind_type: message type. For details, see <b>nwy_network.h</b> . ind_struct: message structure pointer
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_get\_forbidden\_plmn

<b>Function</b>	int nwy_nw_get_forbidden_plmn(nwy_nw_fplmn_list_t *fplmn_list)
<b>Description</b>	To obtain the list of Forbidden PLMN
<b>Parameter</b>	fplmn_list: obtained FPLMN list.
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_manual\_network\_scan

<b>Function</b>	int nwy_nw_manual_network_scan(nwy_nw_net_scan_cb_funcscan_cb)
<b>Description</b>	To scan networks manually It is an asynchronous function. Its scanning result is returned by calling the callback function.
<b>Parameter</b>	scan_cb: callback function. After networks are scanned, this function returns the scanning result.
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_manual\_network\_select

<b>Function</b>	int nwy_nw_manual_network_select(nwy_nw_net_select_param_t *net_select)
<b>Description</b>	To register to a network manually Register a network in the list that is obtained by calling <b>nwy_nw_manual_network_scan</b> .
<b>Parameter</b>	net_select: parameters of the network to be register to, including network PLMN and wireless access technologies.
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_nw\_band\_lock

<b>Function</b>	int nwy_nw_band_lock(uint32_t act, const char *set_band)
<b>Description</b>	To lock the module to one or multiple frequency bands
<b>Parameter</b>	act: 2: GSM 4: LTE set_band: frequency band to be locked, hexadecimal value. For example,

	nwy_nw_band_lock (4,"c000000004"), indicating that the module is locked to LTE B3, B39, and B40 . (You can query the list of frequency bands supported through AT+BANDLOCK or AT+NBANDLOCK. A maximum of five frequency bands can be set simultaneously)
<b>Return value</b>	Successful: 0 Failed: error codes

### nwy\_nw\_freq\_lock

<b>Function</b>	int nwy_nw_freq_lock(uint16_t *nfreq, int n)
<b>Description</b>	To lock single or multiple frequency channels A maximum of 9 ARFCNs can be locked simultaneously
<b>Parameter</b>	nfreq: frequency channel to be locked. n refers to the quantity of the frequency channels.
<b>Return value</b>	Successful: 0 Failed: error codes

### nwy\_nw\_get\_IMS\_state

<b>Function</b>	int nwy_nw_get_IMS_state(uint8_t* on_off)
<b>Description</b>	To obtain the current IMS status
<b>Parameter</b>	on_off: status of IMS 1: enabled 0: disabled
<b>Return value</b>	Successful: 0 Failed: error codes

### nwy\_nw\_set\_IMS\_state

<b>Function</b>	int nwy_nw_set_IMS_state(uint8_t on_off)
<b>Description</b>	To enable or disable the IMS function
<b>Parameter</b>	on_off: status of IMS to be set 1: enable 0: disable
<b>Return value</b>	Successful: 0 Failed: error codes Before setting IMS, lock the network mode to <b>LTE ONLY</b> . Otherwise, errors will be returned.

## nwy\_nw\_get\_signal\_rssi

<b>Format</b>	int nwy_nw_get_signal_rssi(uint8_t *rssi)
<b>Description</b>	To obtain the actual RSSI value of the current network
<b>Parameter</b>	rssi: RSSI value of the current network
<b>Return value</b>	Successful: 0 Failed: an error code

## nwy\_nw\_get\_netmsg

<b>Format</b>	int nwy_nw_get_netmsg (nwy_serving_cell_info *pNetmsg)
<b>Description</b>	To obtain the information of the current serving cell.
<b>Parameter</b>	pNetmsg: Current network service cell information structure pointer
<b>Return value</b>	Successful: 0 Failed: an error code

## nwy\_nw\_get\_cfgdftpdn\_info

<b>Format</b>	int nwy_nw_get_cfgdftpdn_info(nwy_nw_cfgdftpdn_t* cfgdftpdn_info)
<b>Description</b>	To obtain the current default bearer PDN information.
<b>Parameter</b>	cfgdftpdn_info: current default bearer PDN information obtained.
<b>Return value</b>	Successful: 0 Failed: an error code

## nwy\_nw\_set\_cfgdftpdn\_info

<b>Format</b>	int nwy_nw_set_cfgdftpdn_info(nwy_nw_cfgdftpdn_t* cfgdftpdn_info)
<b>Description</b>	To set the current default bearer PDN information.
<b>Parameter</b>	cfgdftpdn_info: Current default bearer PDN information that is set.
<b>Return value</b>	Successful: 0 Failed: an error code



## nwy\_nw\_get\_default\_pdn\_apn

<b>Format</b>	char* nwy_nw_get_default_pdn_apn()
<b>Description</b>	To obtain the default bearer APN.
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: first address of the APN information string Failed: an error code

## nwy\_nw\_get\_neighborLocatorInfo

<b>Format</b>	int nwy_nw_get_neighborLocatorInfo(nwy_locator_report_cb report_cb)
<b>Description</b>	To obtain the neighbor cell information.
<b>Parameter</b>	report_cb: callback function, after the scanning finishes, the scanned cell information is reported.
<b>Return value</b>	Successful: 0 Failed: an error code

## 2.4.9 FOTA

FOTA APIs can be found in **nwy\_fota.h**. They are used to perform firmware upgrades when the device is connected to a network.

## nwy\_fota\_update

<b>Function</b>	unsigned int nwy_fota_update(const void *data, unsigned int size)
<b>Description</b>	To write the FOTA upgrade package into the flash of the module
<b>Parameter</b>	data: data pointer of the upgrade package size: size of the upgrade package
<b>Return value</b>	Return the size of the upgrade package that is written into the flash of the module.

## nwy\_version\_update

<b>Function</b>	int nwy_version_update(bool bRst)
<b>Description</b>	To trigger a FOTA upgrade
<b>Parameter</b>	bRst: flag of immediate restarting true: after the upgrade package is verified, the upgrade is triggered and the module restarts immediately to upgrade.

	false: after the upgrade package is verified, the upgrade is triggered and the module is upgraded when restarting.
<b>Return value</b>	Successful: 0 Failed: error codes

### nwy\_get\_update\_result

<b>Function</b>	int nwy_get_update_result(void)
<b>Description</b>	To query whether the firmware is upgraded successfully
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: 0 Failed: error codes

## 2.4.10 Virtual AT

AT APIs can be found in **nwy\_vir\_at.h**. They are used to transmit and receive AT commands.

### nwy\_sdk\_at\_parameter\_init

<b>Function</b>	void nwy_sdk_at_parameter_init()
<b>Description</b>	To initialize the virtual AT function
<b>Parameter</b>	N/A
<b>Return value</b>	void

### nwy\_sdk\_at\_cmd\_send

<b>Function</b>	int nwy_sdk_at_cmd_send(nwy_at_info *pInfo, char *resp, int timeout)
<b>Description</b>	To send AT commands
<b>Parameter</b>	pInfo: pointer that points to the information to be sent through the AT command resp: Return value timeout: timeout period ranges from 5 to 30s.
<b>Return value</b>	Successful: 0 Failed: error codes

## nwy\_sdk\_at\_unsolicited\_cb\_reg

<b>Function</b>	int nwy_sdk_at_unsolicited_cb_reg(char *at_prefix, void *p_func);
<b>Description</b>	To register an unsolicited report function
<b>Parameter</b>	at_prefix: character string reported in an unsolicited manner p_func: function used to process the unsolicited report
<b>Return value</b>	Successful: 0 Failed: error codes

## 2.4.11 Socket

Socket APIs can be found in **nwy\_socket.h**.

## nwy\_socket\_open

<b>Function</b>	int nwy_socket_open (int domain, int type, int protocol);
<b>Description</b>	To create and open a socket
<b>Parameter</b>	Domain: protocol family 0: AF_UNSPEC 1: AF_INET AF_INET6 = 0 Type: socket types 1: SOCK_STREAM 2: SOCK_DGRAM 3: SOCK_RAW Protocol: protocol types 6: IPPROTO_TCP 17: IPPROTO_UDP
<b>Return value</b>	Socket descriptors

## nwy\_socket\_send

<b>Function</b>	int nwy_socket_send(int s, const void *data, size_t size, int flags);
<b>Description</b>	To send data through a socket
<b>Parameter</b>	s: socket descriptor data: data to be sent size: content size flags: 0 generally

<b>Return value</b>	Successful: the quantity of received bytes Failed: error code (a value lower than 0)
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## nwy\_socket\_recv

<b>Function</b>	int nwy_socket_recv(int s, void *mem, size_t len, int flags);
<b>Description</b>	To receive data through a socket
<b>Parameter</b>	s: socket descriptor mem: the buffer that is used to store the received data len: data length flags: set to 0 generally
<b>Return value</b>	Successful: the quantity of received bytes Failed: error codes (a value lower than 0)

## nwy\_socket\_sendto

<b>Function</b>	int nwy_socket_sendto(int s, const void *data, size_t size, int flags, const struct sockaddr *to, socklen_t tolen)
<b>Description</b>	To send data to the destination address
<b>Parameter</b>	s: socket descriptor data: the buffer that is used to store the received data size: data length flags: 0 generally to: destination address and port number tolen: address length
<b>Return value</b>	Successful: the quantity of received bytes Failed: error codes (a value lower than 0)

## nwy\_socket\_recvfrom

<b>Function</b>	int nwy_socket_recvfrom(int s, void *mem, size_t len, int flags, struct sockaddr *from, socklen_t *fromlen);
<b>Description</b>	To receive data from the source address
<b>Parameter</b>	s: socket descriptor mem: the buffer that is used to store the received data len: data length flags: set to 0 generally from: the source address and the source port number fromlen: address length

<b>Return value</b>	Successful: the quantity of received bytes Failed: error codes (a value lower than 0)
---------------------	--

### nwy\_socket\_setsockopt

<b>Function</b>	int nwy_socket_setsockopt(int s, int level, int optname, const void * optval, socklen_t optlen);
<b>Description</b>	To set the value of socket options
<b>Parameter</b>	s: socket descriptor level: a protocol level that the option pertains to optname: name of the option to be accessed optval: points to the buffer that contains new options optlen: option length
<b>Return value</b>	Successful: 0 Failed: others

### nwy\_socket\_getsockopt

<b>Function</b>	int nwy_socket_getsockopt(int s, int level, int optname, void * optval, socklen_t * optlen);
<b>Description</b>	To return the value of socket options
<b>Parameter</b>	s: socket descriptor level: a protocol level that the option pertains to optname: name of the option to be accessed optval: points to the buffer that returns new options optlen: maximum length of the option value
<b>Return value</b>	Successful: 0 Failed: others

### nwy\_gethostbyname

<b>Function</b>	char* nwy_gethostbyname (const char *name);
<b>Description</b>	To obtain the host address according to the domain name
<b>Parameter</b>	name: domain name
<b>Return value</b>	Failed: NULL

## nwy\_gethostbyname1

<b>Function</b>	char* nwy_gethostbyname1 (const char *name, int *isipv6);
<b>Description</b>	To obtain the host address according to the domain name
<b>Parameter</b>	name: domain name isipv6: used to determine whether the returned address adopts IPv6
<b>Return value</b>	Failed: NULL

## nwy\_socket\_close

<b>Function</b>	int nwy_socket_close(int socket);
<b>Description</b>	To close the socket
<b>Parameter</b>	socket: socket descriptor
<b>Return value</b>	Successful: 0 Failed: others

## nwy\_socket\_connect

<b>Function</b>	int nwy_socket_connect(int socket, const struct sockaddr *name, socklen_t namelen);
<b>Description</b>	To create a socket link
<b>Parameter</b>	socket: socket descriptor name: server socket namelen: name length of the server socket
<b>Return value</b>	Successful: 0 Failed: others

## nwy\_socket\_bind\_lport

<b>Function</b>	int nwy_socket_bind_lport(int socket, uint16_t lport)
<b>Description</b>	To bind to a socket
<b>Parameter</b>	socket: socket descriptor lport: port number
<b>Return value</b>	Successful: 0 Failed: others

## nwy\_socket\_bind

<b>Function</b>	int nwy_socket_bind(int socket, struct sockaddr *addr, socklen_t *addrlen)
<b>Description</b>	To bind to a socket link
<b>Parameter</b>	socket: socket descriptor addr: socket address addrlen: address length
<b>Return value</b>	Successful: 0 Failed: others

## nwy\_socket\_listen

<b>Function</b>	int nwy_socket_listen(int socket, int backlog)
<b>Description</b>	To set a socket to listen
<b>Parameter</b>	socket: socket descriptor backlog: maximum quantity of clients that the socket can listen to
<b>Return value</b>	Successful: 0 Failed: others

## nwy\_socket\_accept

<b>Function</b>	int nwy_socket_accept (int socket, struct sockaddr *addr, socklen_t *addrlen)
<b>Description</b>	To accept a connection request from a socket.
<b>Parameter</b>	socket: socket descriptor addr: socket information addrlen: address length
<b>Return value</b>	Successful: 0 Failed: others

## nwy\_socket\_select

<b>Function</b>	int nwy_socket_select(int maxfdp1, fd_set *readset, fd_set *writerset, fd_set *exceptset, struct timeval *timeout)
<b>Description</b>	To select a socket to listen
<b>Parameter</b>	maxfdp1: range of all the file descriptors, that is, the maximum value of the file descriptor plus 1. readset: to monitor the read status of file descriptors Value greater than 0 indicates there are readable files

	<p>writeset: to monitor the write status of file descriptors, value greater than 0 indicates there are writeable files.</p> <p>exceptset: to monitor file abnormalities</p> <p>timeout: timeout period of the select function.</p> <ul style="list-style-type: none"> <li>• NULL: the select function blocks</li> <li>• 0 seconds 0 ms: the select function is set to a pure non-blocking function. Regardless of whether the file descriptor changes, a value is returned immediately to continue performing its function. If the file does not change, 0 is returned. If the file changes, a positive value is returned.</li> <li>• A value greater than 0: timeout period If an event occurs within the period, a value greater than 0 is returned. A value must be returned when the timeout period is over.</li> </ul>
<b>Return value</b>	<ul style="list-style-type: none"> <li>• The select function encounters abnormalities: a value lower than 0 is returned.</li> <li>• Some files can be read or written: a value greater than 0 is returned.</li> <li>• The function times out and no files can be read or written or the files are wrong: 0 is returned.</li> </ul>

### nwy\_socket\_shutdown

<b>Function</b>	int nwy_socket_shutdown(int s, int how)
<b>Description</b>	To close a socket.
<b>Parameter</b>	s: socket descriptor how: SHUT_RD SHUT_WR SHUT_RDWR
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_socket\_get\_ack

<b>Format</b>	int nwy_socket_get_ack(int socket);
<b>Description</b>	To obtain the total length of data that is successfully received by the peer device.
<b>Parameter</b>	socket: socket descriptor
<b>Return value</b>	the total length of data that is successfully received by the peer device.

### nwy\_socket\_get\_sent

<b>Format</b>	int nwy_socket_get_sent(int socket);
<b>Description</b>	To obtain the total length of data sent by the socket
<b>Parameter</b>	socket: socket descriptor



<b>Return value</b>	the total length of data sent by the socket
---------------------	---

### nwy\_socket\_bind\_netif

<b>Format</b>	int nwy_socket_bind_netif(int sockid, int simid, int cid);
<b>Description</b>	To bind the socket to a specific data link.
<b>Parameter</b>	socket: socket descriptor simid: SIM card ID cid: profile ID
<b>Return value</b>	Failed: -1 Successful: 0

## 2.4.12 FTP

FTP APIs can be found **nwy\_ftp.h**.

### nwy\_ftp\_login

<b>Function</b>	int nwy_ftp_login(nwy_ftp_login_t *ftp_param, resultcb cb)
<b>Description</b>	To log in to the FTP service.
<b>Parameter</b>	nwy_ftp_login_t *ftp_param, resultcb: see <b>nwy_ftp.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_ftp\_get

<b>Function</b>	int nwy_ftp_get(const char* filename, uint8_t type, int offset, int len)
<b>Description</b>	To download data form the FTP server.
<b>Parameter</b>	const char* filename, uint8_t type, int offset, int len, see <b>nwy_ftp.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_ftp\_put

<b>Function</b>	int nwy_ftp_put(const char* filename, uint8_t type ,uint8_t mode, const char *data, int len)
-----------------	--

<b>Description</b>	To upload data form the FTP server.
<b>Parameter</b>	const char* filename, uint8_t type , uint8_t mode, const char *data, int len: see <b>nwy_ftp.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_ftp\_filesiz

<b>Function</b>	int nwy_ftp_filesize(const char* filename, uint16 tout)
<b>Description</b>	To query the file size of the FTP server.
<b>Parameter</b>	const char* filename, uint16 tout: see <b>nwy_ftp.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_ftp\_logout

<b>Function</b>	int nwy_ftp_logout(uint16 tout)
<b>Description</b>	To log out form the FTP server.
<b>Parameter</b>	uint16 tout: time-out period
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_multiplex\_ftp\_login

<b>Format</b>	int nwy_ multiplex_ftp_login(nwy_ftp_login_t *ftp_param, resultcb cb)
<b>Description</b>	To log in to the FTP server.
<b>Parameter</b>	uint16_t channel , nwy_ multiplex_ftp_login_t *ftp_param, resultcb cb, for detail, see nwy_ftp.h.
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_multiplex\_ftp\_get

<b>Format</b>	int nwy_ multiplex_ftp_get(uint16_t channel, const char* filename, uint8_t type, int offset, int len)
<b>Description</b>	To download data from the FTP server.

<b>Parameter</b>	uint16_t channel , const char* filename, uint8_t type, int offset, int len, for details, see nwy_ftp.h.
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_multiplex\_ftp\_put

<b>Format</b>	int nwy_ multiplex_ftp_put(uint16_t channel, const char* filename, uint8_t type ,uint8_t mode, const char *data, int len)
<b>Description</b>	To upload data to the FTP server.
<b>Parameter</b>	uint16_t channel , const char* filename, uint8_t type , uint8_t mode, const char *data, int len, for details, see nwy_ftp.h.
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_multiplex\_ftp\_filesiz

<b>Format</b>	int nwy_ multiplex_ftp_filesize(uint16_t channel, const char* filename, uint16_t tout)
<b>Description</b>	To query the size of the file in the FTP server,
<b>Parameter</b>	uint16_t channel, const char* filename, uint16_t tout, for details, see nwy_ftp.h.
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_multiplex\_ftp\_logout

<b>Format</b>	int nwy_ multiplex_ftp_logout(uint16_t channel,uint16_t tout)
<b>Description</b>	To log out from the FTP server.
<b>Parameter</b>	uint16_t channel: channel number uint16_t tout: timeout period
<b>Return value</b>	Successful: 0 Failed: -1

## 2.4.13 HTTP/HTTPS

HTTP/HTTPS APIs can be found in `nwy_http.h`.

### nwy\_http\_setup

<b>Function</b>	<code>int nwy_http_setup(uint16_t channel, const char *url, int port, httpresultcb cb)</code>
<b>Description</b>	To establish an HTTP connection.
<b>Parameter</b>	channel: ranging from 0 to 7. url: destination URL port: destination port cb: callback function of event notification, see <code>nwy_http.h</code> .
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_http\_setup\_ex

<b>Format</b>	<code>int nwy_http_setup_ex(uint16_t channel, const char *url, int port, void *context, httpresultcb_ex cb)</code>
<b>Description</b>	To set up an HTTP connection (support adding custom parameters).
<b>Parameter</b>	uint16_t channel: channel number ranges from 0 to 7. const char *url: destination path int port: destination port number void *context: custom parameter of upper layer httpresultcb_ex cb: callback function of the event notification, for details, see <code>nwy_http.h</code> .
	<code>typedef void (*httpresultcb_ex)(nwy_http_result_t *event, void *context); //notify events</code>
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_https\_setup

<b>Function</b>	<code>int nwy_https_setup(uint16_t channel, const char *url, int port, httpresultcb cb, nwy_app_ssl_conf_t *ssl_cfg)</code>
<b>Description</b>	To establish an HTTPS connection.
<b>Parameter</b>	channel: ranging from 0 to 7. url: destination URL

	port: destination port cb: callback function of event notification, see <b>nwy_http.h</b> . *ssl_cfg for the information of SSL configuration, see <b>nwy_http.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_http\_get

<b>Function</b>	int nwy_http_get(uint8_t keepalive, int offset, int size, boolean is_https);
<b>Description</b>	To initiate a GET request.
<b>Parameter</b>	keepalive: determines whether the connection is a long connection offset: specifies the start position of download. size: specifies the download size. boolean is_https: True: HTTPS False: HTTP see <b>nwy_http.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_http\_head

<b>Function</b>	int nwy_http_head(uint8_t keepalive, boolean is_https)
<b>Description</b>	To initiate a HEAD request.
<b>Parameter</b>	keepalive: determines whether the connection is a long connection boolean is_https: True: HTTPS False: HTTP see <b>nwy_http.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_http\_post

<b>Function</b>	int nwy_http_post(uint8_t keepalive, uint8_t type, const char* data, int len, Boolean is_https)
<b>Description</b>	To initiate a POST request.
<b>Parameter</b>	keepalive: determines whether the connection is a long connection.

	type: data packet type data: post data len: data length boolean is_https: True: HTTPS False: HTTP see <b>nwy_http.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_http\_close

<b>Function</b>	int nwy_http_close(boolean is_https)
<b>Description</b>	To close a connection unsolicitedly.
<b>Parameter</b>	boolean is_https: True: HTTPS False: HTTP see <b>nwy_http.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_multiplex\_http\_setup

<b>Format</b>	int nwy_ multiplex_http_setup(uint16_t channel, const char *url, int port, httpresultcb cb)
<b>Description</b>	To set up an HTTP connection.
<b>Parameter</b>	uint16_t channel: channel number ranging from 1 to 7. const char *url: destination path int port: destination port number httpresultcb cb: callback function of the event notification, for details, see nwy_http.h.
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_multiplex\_https\_setup

<b>Format</b>	int nwy_ multiplex_https_setup(uint16_t channel, const char *url, int port, httpresultcb cb, nwy_app_ssl_conf_t *ssl_cfg)
---------------	---

<b>Description</b>	To set up an HTTPS connection.
<b>Parameter</b>	<p>uint16_t channel: channel number ranging from 1 to 7.</p> <p>const char *url: destination path</p> <p>int port: destination port number</p> <p>httresultcb cb: callback function of the event notification, for details, see nwy_http.h.</p> <p>nwy_app_ssl_conf_t *ssl_cfg SSL: for the specific definition of configuration information, see nwy_http.h.</p>
<b>Return value</b>	<p>Successful: 0</p> <p>Failed: -1</p>

### nwy\_multiplex\_http\_get

<b>Format</b>	int nwy_multiplex_http_get(uint16_t channel, uint8_t keepalive, int offset, int size, boolean is_https);
<b>Description</b>	To initiate a GET request.
<b>Parameter</b>	<p>uint16_t channel: channel number ranges from 1 to 7.</p> <p>uint8_t keepalive: whether it is a long connection.</p> <p>int offset: specifies the starting position of the download.</p> <p>int size: specifies the length of the data downloaded.</p> <p>boolean is_https:</p> <p>True: HTTPS</p> <p>False: HTTP</p> <p>For details, see nwy_http.h.</p>
<b>Return value</b>	<p>Successful: 0</p> <p>Failed: -1</p>

### nwy\_multiplex\_http\_head

<b>Format</b>	int nwy_multiplex_http_head(uint16_t channel, uint8_t keepalive, boolean is_https)
<b>Description</b>	To initiate a HEAD request.
<b>Parameter</b>	<p>uint16_t channel: channel number ranges from 1 to 7.</p> <p>uint8_t keepalive: whether it is a long connection.</p> <p>boolean is_https:</p> <p>True: HTTPS</p> <p>False: HTTP</p> <p>For details, see nwy_http.h.</p>
<b>Return value</b>	<p>Successful: 0</p> <p>Failed: -1</p>

## nwy\_multiplex\_http\_post

<b>Format</b>	int nwy_multiplex_http_post(uint16_t channel, uint8_t keepalive, uint8_t type, const char* data, int len, Boolean is_https)
<b>Description</b>	To initiate a POST request.
<b>Parameter</b>	uint16_t channel: channel number ranges from 1 to 7. uint8_t keepalive: whether it is a long connection. uint8_t type: message type const char* data: post data. int len: data length boolean is_https: True: HTTPS False: HTTP For details, see nwy_http.h.
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_multiplex\_http\_close

<b>Format</b>	int nwy_multiplex_http_close(uint16_t channel, boolean is_https)
<b>Description</b>	To proactively close the connection.
<b>Parameter</b>	uint16_t channel: channel number ranges from 1 to 7. boolean is_https: True: HTTPS False: HTTP
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_cert\_add

<b>Function</b>	int nwy_cert_add(const char *file_name, const char *data, int length)
<b>Description</b>	To add the SSL certificate.
<b>Parameter</b>	file_name: name of the certificate. The certificate will be stored in <b>/nwy/</b> . data: certificate content length: length of the certificate content For details, see <b>nwy_http.h</b> .
<b>Return value</b>	Successful: 0 Failed: -1



## nwy\_cert\_check

<b>Function</b>	int nwy_cert_check(const char *file_name)
<b>Description</b>	To validate the SSL certificate.
<b>Parameter</b>	file_name: name of the certificate.
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_cert\_del

<b>Function</b>	int nwy_cert_del(const char *file_name)
<b>Description</b>	To delete the SSL certificate.
<b>Parameter</b>	file_name: name of the certificate.
<b>Return value</b>	Successful: 0 Failed: -1

## 2.4.14 BLE

The definitions of these API functions can be found in nwy\_ble.h. They are used to perform the BLE-related functions.

## nwy\_ble\_enable

<b>Format</b>	int nwy_ble_enable();
<b>Description</b>	To enable the Bluetooth.
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: 1 Failed: 0

## nwy\_ble\_set\_adv

<b>Format</b>	int nwy_ble_set_adv(bool enable);
<b>Description</b>	To enable/disable the Bluetooth broadcast.
<b>Parameter</b>	enable: 1: enable 0: disable

<b>Return value</b>	Successful: 1 Failed: 0
---------------------	----------------------------

## nwy\_ble\_send\_data

<b>Format</b>	int nwy_ble_send_data(uint16 datalen, char *data);
<b>Description</b>	Send data over BLE.
<b>Parameter</b>	datalen: data length data: data to be sent.
<b>Return value</b>	Successful: 1 Failed: 0

## nwy\_read\_ble\_status

<b>Format</b>	int nwy_read_ble_status();
<b>Description</b>	To read the current BLE status.
<b>Parameter</b>	N/A.
<b>Return value</b>	enable: 1 disable: 0

## nwy\_ble\_disable

<b>Format</b>	int nwy_ble_disable();
<b>Description</b>	To disable the Bluetooth.
<b>Parameter</b>	N/A.
<b>Return value</b>	Successful: 1

## nwy\_ble\_receive\_data

<b>Format</b>	Char * nwy_ble_receive_data(int sel);
<b>Description</b>	To receive data.
<b>Parameter</b>	sel: select the data returned
<b>Return value</b>	sel=0, return recv_length, length of the data received. sel=1, return nwy_ble_8910_tp_data_value, the data received. sel= one of other values, return 0 after the data receiving space is cleared.

## nwy\_ble\_get\_version

<b>Format</b>	int nwy_ble_get_version(char *version);
<b>Description</b>	To obtain the BLE version information.
<b>Parameter</b>	version: version information that is obtained.
<b>Return value</b>	version information

## nwy\_ble\_set\_device\_name

<b>Format</b>	int nwy_ble_set_device_name(char * local_name);
<b>Description</b>	To set the BLE device name.
<b>Parameter</b>	local_name: device name
<b>Return value</b>	Successful: 1 Failed: 0

## nwy\_ble\_get\_device\_name

<b>Format</b>	int nwy_ble_get_device_name(uint16 *device_name);
<b>Description</b>	To obtain the BLE device name.
<b>Parameter</b>	name: device name obtained
<b>Return value</b>	N/A.

## nwy\_ble\_update\_conn

<b>Format</b>	int nwy_ble_update_conn(uint16 handle, uint16 intervalMin, uint16 intervalMax, uint16 slaveLatency, uint16 timeoutMulti);
<b>Description</b>	To update the BLE connection parameters.
<b>Parameter</b>	Handle: connection handle IntervalMin: the minimum interval, unit: 1.25 ms, ranges from 7.5 ms to 4s. IntervalMax: the maximum interval, unit: 1.25 ms, ranges from 7.5 ms to 4s, IntervalMin<= intervalMax. slaveLatency: latency timeoutMulti: timeout period of the connection, unit: 10ms, ranges from 100 ms to 32s
<b>Return value</b>	N/A.

## nwy\_ble\_register\_callback

<b>Format</b>	int nwy_ble_register_callback(void (*ble_reg_cb)
<b>Description</b>	To register the data callback function.
<b>Parameter</b>	Ble_reg_cb: callback function
<b>Return value</b>	Successful: 1

## nwy\_set\_manufacture

<b>Format</b>	int nwy_set_manufacture (UINT8 Manufacture_Data[8])
<b>Description</b>	To customize the data parameter of manufacture.
<b>Parameter</b>	Manufacture_Data[8], the data parameter
<b>Return value</b>	Successful: 1

## nwy\_ble\_beacon

<b>Format</b>	int nwy_ble_beacon (UINT8 uuid[16],UINT8 major[2],UINT8 minor[2])
<b>Description</b>	Beacon function
<b>Parameter</b>	UINT8 uuid[16],UINT8 major[2],UINT8 minor[2], the Beacon parameter
<b>Return value</b>	Successful: 1 Failed: 0

## nwy\_ble\_set\_service

<b>Format</b>	int nwy_ble_set_service (uint32_t srv_uuid[])
<b>Description</b>	To set the UUID service.
<b>Parameter</b>	srv_uuid[], the UUID service that is set.
<b>Return value</b>	Successful: 1 Failed: 0

## nwy\_ble\_set\_character

<b>Format</b>	int nwy_ble_set_character (UINT8 char_index,uint32_t char_uuid[],uint8_t prop)
<b>Description</b>	To set the character information.
<b>Parameter</b>	char_index: character index char_uuid[]: character UUID

	prop: character property
<b>Return value</b>	Successful: 1 Failed: 0

## 2.4.15 Standard MQTT

The definitions of these API functions can be found in MQTTClient.h and nwy\_mqtt.h. They are used to perform the Standard MQTT related functions.

### MQTTIsConnected

<b>Format</b>	int MQTTIsConnected(MQTTClient* client)
<b>Description</b>	To obtain the MQTT connection status.
<b>Parameter</b>	client: MQTT instance
<b>Return value</b>	Successful: 0 Failed: other values

### NetworkInit

<b>Format</b>	void NetworkInit(Network* n)
<b>Description</b>	To initialize the network
<b>Parameter</b>	n: network connection parameters
<b>Return value</b>	N/A.

### MQTTClientInit

<b>Format</b>	void MQTTClientInit(MQTTClient* c, Network* network, unsigned int command_timeout_ms, unsigned char* sendbuf, size_t sendbuf_size, unsigned char* readbuf, size_t readbuf_size)
<b>Description</b>	To initialize the MQTT instance.
<b>Parameter</b>	c: MQTT instance network: network connection parameter command_timeout_ms: timeout period sendbuf: sending buff sendbuf_size: size of the sending buffer readbuf: reading buffer readbuf_size: size of the reading buffer

<b>Return value</b>	N/A.
---------------------	------

## NetworkConnect

<b>Format</b>	int NetworkConnect(Network* n, char* addr, int port)
<b>Description</b>	To establish a network connection.
<b>Parameter</b>	n: network connection parameters addr: URL of the server. port: port number of the server.
<b>Return value</b>	Successful: 0 Failed: other values

## MQTTClientInit\_defaultMessage

<b>Format</b>	void MQTTClientInit_defaultMessage(MQTTClient* client, messageHandler messageHandler)
<b>Description</b>	To register the callback function.
<b>Parameter</b>	client: MQTT instance messageHandler: message processing function
<b>Return value</b>	N/A.

## nwy\_MQTTConnect

<b>Format</b>	int nwy_MQTTConnect(MQTTClient* c, MQTTPacket_connectData* options)
<b>Description</b>	To set up an MQTT connection.
<b>Parameter</b>	c: MQTT instance options: connection parameter, including client identifier, user name, password, security time, and so on.
<b>Return value</b>	Successful: 0 Failed: other values

## nwy\_MQTTPublish

<b>Format</b>	int nwy_MQTTPublish(MQTTClient* c, const char* topicName, MQTTMessage* message)
<b>Description</b>	To publish an MQTT message.

<b>Parameter</b>	c: MQTT instance topicName: topic name message: message body, including the message, message length, retained mark, and so on.
<b>Return value</b>	Successful: 0 Failed: other values

## MQTTSubscribe

<b>Format</b>	int MQTTSubscribe(MQTTClient* c, const char* topicFilter, enum QoS qos, messageHandler messageHandler)
<b>Description</b>	MQTT subscribes the topic. To register the message reporting processing function.
<b>Parameter</b>	c: MQTT instance topicFilter: topic name qos: quality of service. messageHandler: message processing function
<b>Return value</b>	Successful: 0 Failed: other values

## MQTTUnsubscribe

<b>Format</b>	int MQTTUnsubscribe(MQTTClient* c, const char* topicFilter)
<b>Description</b>	To cancel a subscription.
<b>Parameter</b>	c: MQTT instance topicFilter: topic name
<b>Return value</b>	Successful: 0 Failed: other values

## MQTTDisconnect

<b>Format</b>	int MQTTDisconnect(MQTTClient* c)
<b>Description</b>	To disconnect the MQTT connection and release the resource.
<b>Parameter</b>	c: MQTT instance
<b>Return value</b>	Successful: 0 Failed: other values

## NetworkDisconnect

<b>Format</b>	void NetworkDisconnect(Network* n)
<b>Description</b>	To close the network connection.
<b>Parameter</b>	n: network connection parameters
<b>Return value</b>	N/A.

## MQTTYield

<b>Format</b>	int MQTTYield(MQTTClient* c, int timeout_ms)
<b>Description</b>	To receive network messages and distribute the messages to the user's callback function.
<b>Parameter</b>	c: MQTT instance timeout_ms: timeout period of the receive message.
<b>Return value</b>	0

## 2.4.16 Alibaba MQTT

The definitions of these API functions can be found in `mqtt_api.h`. They are used to perform the Alibaba MQTT related functions.

## IOT\_SetupConnInfo

<b>Format</b>	int IOT_SetupConnInfo(const char *product_key, const char *device_name, const char *device_secret, void **info_ptr)
<b>Description</b>	To set the IoT connection parameters.
<b>Parameter</b>	product_key: secret key Device_name: device name device_secret: info_ptr: info structure
<b>Return value</b>	N/A.

## IOT\_MQTT\_CheckStateNormal

<b>Format</b>	int IOT_MQTT_CheckStateNormal(void *handle)
---------------	---



<b>Description</b>	To obtain the IoT connection status.
<b>Parameter</b>	handle: IoT instance
<b>Return value</b>	1 indicates the connection is established.

### IOT\_MQTT\_Construct

<b>Format</b>	void *IOT_MQTT_Construct(MQTTInitParams *pParams)
<b>Description</b>	To create the instance and connect to the server.
<b>Parameter</b>	n: network connection parameters addr: URL of the server. port: port number of the server.
<b>Return value</b>	Successful: 0 Failed: other values

### IOT\_MQTT\_Subscribe

<b>Format</b>	int IOT_MQTT_Subscribe(void *handle, const char *topic_filter, iotx_mqtt_qos_t qos, iotx_mqtt_event_handle_func_fpt topic_handle_func, void *pcontext)
<b>Description</b>	To subscribe a topic.
<b>Parameter</b>	handle: IoT instance topic_filter: topic name qos: quality of service. topic_handle_func: report handling function pcontext: user context, it will be sent back through the callback function.
<b>Return value</b>	Successful: 0 Failed: a value < 0

### IOT\_MQTT\_Publish

<b>Format</b>	int IOT_MQTT_Publish(void *handle, const char *topic_name, iotx_mqtt_topic_info_pt topic_msg)
<b>Description</b>	To publish a message.
<b>Parameter</b>	handle: IoT instance topic_filter: topic name topic_msg: message body

<b>Return value</b>	Successful: 0
	When the message is QoS1, the Return value is the MQTT message ID of the reported message.
	Failed: other values

## IOT\_MQTT\_Unsubscribe

<b>Format</b>	int IOT_MQTT_Unsubscribe(void *handle, const char *topic_filter);
<b>Description</b>	To cancel a subscription.
<b>Parameter</b>	handle: IoT instance topic_filter: topic name
<b>Return value</b>	Successful: 0 Failed: a value < 0

## IOT\_MQTT\_Destroy

<b>Format</b>	int IOT_MQTT_Destroy(void **pClient)
<b>Description</b>	To disconnect the connection, destroy the instance, and release the resource.
<b>Parameter</b>	pClient: IoT instance
<b>Return value</b>	Successful: 0 Failed: other values

## IOT\_MQTT\_Yield

<b>Format</b>	int IOT_MQTT_Yield(void *handle, int timeout_ms);
<b>Description</b>	To receive network messages and distribute the messages to the user's callback function.
<b>Parameter</b>	handle: IoT instance timeout_ms: timeout period of the receive message.
<b>Return value</b>	0

## 2.4.17 Websocket

The definitions of these API functions can be nwy\_rws\_proc.h. They are used to perform the websocket-related functions.

### nwy\_ws\_open

<b>Format</b>	void *nwy_ws_open(const char *url, const nwy_rws_opt_t *opt, nwy_rws_data_fun_cb data_cb, nwy_rws_close_fun_cb close_cb, void *arg);
<b>Description</b>	To open the websocket.
<b>Parameter</b>	url: the URL that is enabled. opt: option when opening websocket typedef struct _nwy_rws_opt { int ping_interval; /* the ping interval,if input,used the value(the unit is second),other used the default value, */ int ping_timeout; /* ping out time ,now not support.*/ int should_handshake;/* if need handshake,the value is 1,other 0 */ char *origin; /* if input,used the origin,other used the host */ char *key; /* if input,used the key ,other used default value */ }nwy_rws_opt_t; data_cb: callback data function typedef void (*nwy_rws_data_fun_cb)(void *t, const void *data, unsigned int len, void *arg); close_cb: the callback function that is used to close the websocket. typedef void (*nwy_rws_close_fun_cb)(void *t,int reason, void *arg);
<b>Return value</b>	Successful: websocket handle Failed: NULL

### nwy\_ws\_send\_binary

<b>Format</b>	int nwy_ws_send_binary(void *ws_client, const void *data, unsigned int size);
<b>Description</b>	To send the binary data..
<b>Parameter</b>	ws_client: websocket handle data: data sent. size: size of the data sent
<b>Return value</b>	Successful: 0 Failed: other values

## nwy\_rws\_send\_text

<b>Format</b>	int nwy_rws_send_text(void *ws_client, const char *data);
<b>Description</b>	To send the text data
<b>Parameter</b>	ws_client: websocket handle data: data sent.
<b>Return value</b>	Successful: 0 Failed: other values

## nwy\_rws\_close

<b>Format</b>	int nwy_rws_close(void * ws_client);
<b>Description</b>	To close the websocket.
<b>Parameter</b>	ws_client: websocket handle
<b>Return value</b>	Successful: 0 Failed: other values

## 2.4.18 Packet manage

The definitions of these API functions can be nwy\_ip\_packet.h. They are used to perform the data package related functions.

## nwy\_get\_rcv\_ip\_packet\_reg

<b>Format</b>	void nwy_get_rcv_ip_packet_reg(nwy_get_ip_packet cb);
<b>Description</b>	To register to receive the IP packet callback function.
<b>Parameter</b>	cb: receive packet processing function
<b>Return value</b>	NA

## nwy\_get\_send\_ip\_packet\_reg

<b>Format</b>	void nwy_get_rcv_ip_packet_reg(nwy_get_ip_packet cb);
<b>Description</b>	To register to send the IP packet callback function.
<b>Parameter</b>	cb: send packet processing function
<b>Return value</b>	NA

## 2.5 System

### 2.5.1 Device Management

DM APIs can be found in `nwy_dm.h`.

#### `nwy_dm_get_dev_model`

<b>Function</b>	<code>int nwy_dm_get_dev_model(char *model_buf, int buf_len);</code>
<b>Description</b>	To get the device information.
<b>Parameter</b>	model_buf: device information buf_len: lengt
<b>Return value</b>	Successful: <code>NWY_SUCESS</code> Failed: others

#### `nwy_dm_get_inner_version`

<b>Function</b>	<code>int nwy_dm_get_inner_version(char *version_buf, int buf_len)</code>
<b>Description</b>	To get the version number.
<b>Parameter</b>	version_buf: version number buf_len: lengt
<b>Return value</b>	Successful: <code>NWY_SUCESS</code> Failed: others

#### `nwy_dm_get_open_sdk_version`

<b>Function</b>	<code>int nwy_dm_get_open_sdk_version(char *version_buf, int buf_len)</code>
<b>Description</b>	To get the version number of the open SDK.
<b>Parameter</b>	version_buf: version number buf_len: lengt
<b>Return value</b>	Successful: <code>NWY_SUCESS</code> Failed: others

### nwy\_dm\_get\_device\_version

<b>Format</b>	void nwy_dm_get_device_version(char* dev_ver, char* lin_ver);
<b>Description</b>	To query the device version number and baseline version number.
<b>Parameter</b>	dev_ver: device version number lin_ver: baseline version number
<b>Return value</b>	NA

### nwy\_dm\_get\_rftemperature

<b>Format</b>	int nwy_dm_get_rftemperature(float *outvalue);
<b>Description</b>	To query the internal temperature of the chip.
<b>Parameter</b>	outvalue: the internal temperature of the chip
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_dm\_get\_hw\_version

<b>Format</b>	void nwy_dm_get_hw_version(char *hw_ver, int buf_len)
<b>Description</b>	To obtain the hardware version number.
<b>Parameter</b>	hw_ver: the hardware version buffer that is stored. buf_len: buffer length
<b>Return value</b>	NA

## 2.5.2 Message Queue

Message queue APIs can be found in **nwy\_osi\_api.h**.

### nwy\_create\_msg\_Queue

<b>Function</b>	nwy_osiMessageQueue_t *nwy_create_msg_Queue(uint32 msg_count, uint32 msg_size)
<b>Description</b>	To initialize the message queue.
<b>Parameter</b>	msg_count: count of the message queues msg_size: size of the message content.
<b>Return value</b>	Failed: NULL Successful: Others

## nwy\_delete\_msg\_que

<b>Function</b>	void nwy_delete_msg_que(nwy_osiMessageQueue_t *mq)
<b>Description</b>	To delete the message queue.
<b>Parameter</b>	mq: message queue
<b>Return value</b>	N/A.

## nwy\_put\_msg\_que

<b>Function</b>	bool nwy_put_msg_que(nwy_osiMessageQueue_t *mq, const void *msg, uint32 timeout)
<b>Description</b>	To send a message
<b>Parameter</b>	mq: message queue msg: message content Timeout: time-out period (unit: ms) 0 indicates always waiting; value will be returned immediately after 0xffffffff message queue is full.
<b>Return value</b>	Successful: true Failed: false

## nwy\_get\_msg\_que

<b>Function</b>	bool nwy_get_msg_que(nwy_osiMessageQueue_t *mq, const void *msg, uint32 timeout)
<b>Description</b>	To accept the message.
<b>Parameter</b>	mq: message queue msg: message content Timeout: time-out period (unit: ms) 0 indicates always waiting; value is returned immediately after 0xffffffff message queue is full.
<b>Return value</b>	Successful: true Failed: false

### nwy\_get\_queue\_pendingevent\_cnt

<b>Format</b>	uint32_t nwy_get_queue_pendingevent_cnt(nwy_osiMessageQueue_t *mq);
<b>Description</b>	To obtain the number of messages stored in the queue.
<b>Parameter</b>	mq: message queue
<b>Return value</b>	the number of messages stored in the message queue

### nwy\_get\_queue\_spaceevent\_cnt

<b>Format</b>	uint32_t nwy_get_queue_spaceevent_cnt(nwy_osiMessageQueue_t *mq);
<b>Description</b>	To obtain the number of idle messages in the queue
<b>Parameter</b>	mq: message queue
<b>Return value</b>	the number of idle messages in the message queue

## 2.5.3 File Operation

File operation APIs can be found in **nwy\_file.h**.

### nwy\_sdk\_fopen

<b>Function</b>	int nwy_sdk_fopen(const char *path, nwy_file_action_e flags);
<b>Description</b>	To open a file.
<b>Parameter</b>	path: file path flags: see <b>nwy_file_action_e</b>
<b>Return value</b>	Successful: return file descriptor Failed: a value <0

### nwy\_sdk\_fclose

<b>Function</b>	int nwy_sdk_fclose(int fd);
<b>Description</b>	To close a file.
<b>Parameter</b>	fd: file descriptor
<b>Return value</b>	Successful: NWY_SUCESS Failed: others



## nwy\_sdk\_fread

<b>Function</b>	uint32 nwy_sdk_fread(int fd, void *dst, uint32 size);
<b>Description</b>	To read a file.
<b>Parameter</b>	fd: file descriptor dst: read data buffer size: number of bytes
<b>Return value</b>	Successful: number of read bytes Failed: others

## nwy\_sdk\_fwrite

<b>Function</b>	uint32 nwy_sdk_fwrite(int fd, const void *data, uint32 size);
<b>Description</b>	To write a file.
<b>Parameter</b>	fd: file descriptor data: data to be written size: number of bytes
<b>Return value</b>	Successful: written data in bytes Failed: others

## nwy\_sdk\_fseek

<b>Function</b>	int nwy_sdk_fseek(int fd, int offset, nwy_fseek_offset_e mode);
<b>Description</b>	To set the file pointer.
<b>Parameter</b>	fd: file descriptor Offset: offset mode: see <b>nwy_fseek_offset_e</b>
<b>Return value</b>	Successful: offset Failed: others

## nwy\_sdk\_fsize

<b>Function</b>	long nwy_sdk_fsize(const char *path);
<b>Description</b>	To get the file size.
<b>Parameter</b>	path: file path
<b>Return value</b>	Successful: the file size in bytes. Failed: others

## nwy\_sdk\_fsize\_fd

<b>Function</b>	int nwy_sdk_fsize_fd(int fd);
<b>Description</b>	To get the file size.
<b>Parameter</b>	fd: file descriptor
<b>Return value</b>	Successful: file size in bytes Failed: -1

## nwy\_sdk\_fexist

<b>Format</b>	bool nwy_sdk_fexist(const char *path);
<b>Description</b>	To determine whether the file exists
<b>Parameter</b>	path: file path
<b>Return value</b>	True: existence False: no existence

## nwy\_sdk\_get\_stat\_path

<b>Format</b>	int nwy_sdk_get_stat_path(const char *path, struct stat *st);
<b>Description</b>	To obtain the file related information according to the file name.
<b>Parameter</b>	path: file name st: file information
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_sdk\_get\_stat\_fd

<b>Format</b>	int nwy_sdk_get_stat_fd(int fd, struct stat *st);
<b>Description</b>	To obtain the file related information according to the file descriptor.
<b>Parameter</b>	fd: file descriptor st: file information
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_sdk\_fsync

<b>Format</b>	int nwy_sdk_fsync(int fd);
<b>Description</b>	To synchronize data in buffer to the file.
<b>Parameter</b>	fd: file descriptor
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_sdk\_ftrunc\_fd

<b>Format</b>	int nwy_sdk_ftrunc_fd(int fd, long len)
<b>Description</b>	To specify the file to be modified to a specific length according to the file descriptor. If the size of the source file is larger than the specified size, the excess part will be deleted.
<b>Parameter</b>	fd: file descriptor len: length of the specified file.
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_sdk\_ftrunc\_path

<b>Format</b>	int nwy_sdk_ftrunc_path(const char *path, long len);
<b>Description</b>	To specify the file to be modified to a specific length according to the file name. If the size of the source file is larger than the specified size, the excess part will be deleted.
<b>Parameter</b>	fd: file descriptor len: length of the specified file.
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_sdk\_file\_unlink

<b>Function</b>	int nwy_sdk_file_unlink(const char* path);
<b>Description</b>	To delete a file
<b>Parameter</b>	path: file path
<b>Return value</b>	Successful: NWY_SUCESS Failed: others

## nwy\_sdk\_frename

<b>Format</b>	int nwy_sdk_frename(const char *oldpath, const char *newpath);
<b>Description</b>	To rename the file.
<b>Parameter</b>	oldpath: the old file name newpath: the new file name
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_sdk\_vfs\_opendir

<b>Format</b>	nwy_dir *nwy_sdk_vfs_opendir(const char *name);
<b>Description</b>	To open a file folder.
<b>Parameter</b>	name: name of the file folder
<b>Return value</b>	Successful: nwy_dir pointer Failed: NULL

## nwy\_sdk\_vfs\_readdir

<b>Format</b>	nwy_dirent *nwy_sdk_vfs_readdir(nwy_dir *pdir);
<b>Description</b>	To read a file folder.
<b>Parameter</b>	pdir: file folder descriptor
<b>Return value</b>	Successful: nwy_dirent pointer Failed: NULL

## nwy\_sdk\_vfs\_telldir

<b>Format</b>	long nwy_sdk_vfs_telldir(nwy_dir *pdir);
<b>Description</b>	The current reading position of the pdir directory stream. The Return value represents the offset from the beginning of the file. The Return value returns the next reading position.
<b>Parameter</b>	pdir: directory flow
<b>Return value</b>	Successful: offset from the beginning Failed: -1

## nwy\_sdk\_vfs\_seekdir

<b>Format</b>	void nwy_sdk_vfs_seekdir(nwy_dir *pdir, long loc);
<b>Description</b>	To set the reading position of the directory stream.
<b>Parameter</b>	pdir: directory flow loc: the offset from the beginning of the directory file
<b>Return value</b>	NA

## nwy\_sdk\_vfs\_rewinddir

<b>Format</b>	void nwy_sdk_vfs_rewinddir(nwy_dir *pdir);
<b>Description</b>	To read the location offset to the position where the directory stream started.
<b>Parameter</b>	pdir: directory flow
<b>Return value</b>	NA

## nwy\_sdk\_vfs\_closedir

<b>Format</b>	int nwy_sdk_vfs_closedir(nwy_dir *pdir)
<b>Description</b>	To close the folder directory flow.
<b>Parameter</b>	pdir: directory flow
<b>Return value</b>	Successful: 0 Failed: -1

## nwy\_sdk\_vfs\_mkdir

<b>Function</b>	int nwy_sdk_vfs_mkdir(const char *name);
<b>Description</b>	To create a directory.
<b>Parameter</b>	path: path of the directory
<b>Return value</b>	Successful: NWY_SUCESS Failed: others

## nwy\_sdk\_vfs\_rmdir

<b>Function</b>	int nwy_sdk_vfs_rmdir(const char *name);
<b>Description</b>	To delete the directory.
<b>Parameter</b>	name: path of the directory

<b>Return value</b>	Successful: NWY_SUCESS Failed: others
---------------------	--

### nwy\_sdk\_vfs\_ls

<b>Function</b>	int nwy_sdk_vfs_ls(void);
<b>Description</b>	To obtain the remaining space size of the user.
<b>Parameter</b>	void
<b>Return value</b>	The remaining space size in bytes.

### nwy\_sdk\_vfs\_free\_size

<b>Format</b>	int nwy_sdk_vfs_free_size(const char *path);
<b>Description</b>	To obtain the remaining space of the file system.
<b>Parameter</b>	Path: base_path: mount point of this block device in the file system.
<b>Return value</b>	The file system mount point

### nwy\_sdk\_sfile\_init

<b>Function</b>	int nwy_sdk_sfile_init(const char *path);
<b>Description</b>	To initialize a secure file operation (power-cut protection).
<b>Parameter</b>	path: file name
<b>Return value</b>	Successful: 0 Failed: -1

### nwy\_sdk\_sfile\_read

<b>Function</b>	long nwy_sdk_sfile_read(const char *path, void *dst, long size);
<b>Description</b>	To initiate a secure file read operation.
<b>Parameter</b>	path: file name dst: buffer used to store the read data size: size of the storage buffer
<b>Return value</b>	Successful: size of the data read Failed: -1

## nwy\_sdk\_sfile\_write

<b>Function</b>	long nwy_sdk_sfile_write(const char *path, void *data, long size);
<b>Description</b>	To initiate a secure file writing operation.
<b>Parameter</b>	path: file name dst: buffer to be written with data size: buffer size
<b>Return value</b>	Successful: size of the data written Failed: -1

## nwy\_sdk\_sfile\_size

<b>Function</b>	long nwy_sdk_sfile_size(const char *path);
<b>Description</b>	To get the size of a secure file.
<b>Parameter</b>	path: file name
<b>Return value</b>	Successful: size of the secure file Failed: -1

## nwy\_sdk\_fread\_path

<b>Function</b>	long nwy_sdk_fread_path(const char *path, void *dst, long size);
<b>Description</b>	To read the file according the file name.
<b>Parameter</b>	pPath: file name dst: buffer to be written with data size: buffer size
<b>Return value</b>	Successful: size of the data read Failed: -1

## nwy\_sdk\_fwrite\_path

<b>Function</b>	long nwy_sdk_fwrite_path(const char *path, void *data, long size);
<b>Description</b>	To write data according to the file name.
<b>Parameter</b>	path: file name dst: buffer to be written with data size: buffer size
<b>Return value</b>	Successful: size of the data written Failed: -1

### nwy\_sdk\_vfs\_rmdir\_recursive

<b>Format</b>	int nwy_sdk_vfs_rmdir_recursive(const char *name)
<b>Description</b>	To forcibly delete a folder.
<b>Parameter</b>	name: name of the file folder
<b>Return value</b>	Successful: 0 Failed: -1

## 2.5.4 Thread

Thread APIs can be found in **nwy\_osi\_api.h**.

### nwy\_create\_thread

<b>Function</b>	nwy_osiThread_t *nwy_create_thread(const char *Name, nwy_osiCallback_t func, void *argument, int32 priority, uint32 stack_size, uint32 event_count);
<b>Description</b>	To create a thread.
<b>Parameter</b>	name        thread name func        thread entry function argument    thread entry function argument priority    thread priority stack_size    thread stack size in byte event_count    thread event queue depth (count of events can be hold)
<b>Return value</b>	Successful: return the thread pointer Failed: NULL

### nwy\_create\_thread\_withstack

<b>Function</b>	nwy_osiThread_t *nwy_create_thread_withstack(const char *name, nwy_osiCallback_t func, void *argument, uint32 priority, void *stack, uint32 stack_size, uint32 event_count);
<b>Description</b>	To create a thread.
<b>Parameter</b>	name        thread name func        thread entry function argument    thread entry function argument priority    thread priority stack        starting address of the stack stack_size    thread stack size in byte



	event_count    thread event queue depth (count of events can be hold)
<b>Return value</b>	Successful: return the thread pointer Failed: NULL

### nwy\_get\_current\_thread

<b>Function</b>	nwy_osiThread_t *nwy_get_current_thread();
<b>Description</b>	To get all tasks of the current function.
<b>Parameter</b>	N/A
<b>Return value</b>	Successful: return the thread pointer Failed: NULL

### nwy\_set\_thread\_priority

<b>Function</b>	bool nwy_set_thread_priority(nwy_osiThread_t *thread, uint32 priority);
<b>Description</b>	To set the priority.
<b>Parameter</b>	thread: thread priority: priority
<b>Return value</b>	Successful: Nwy_SUCCESS Failed: others

### nwy\_get\_thread\_priority

<b>Function</b>	uint32 nwy_get_thread_priority(nwy_osiThread_t *thread);
<b>Description</b>	To get the thread priority.
<b>Parameter</b>	thread: thread
<b>Return value</b>	Successful: thread priority.

### nwy\_suspend\_thread

<b>Function</b>	void nwy_suspend_thread(nwy_osiThread_t *thread);
<b>Description</b>	To suspend a thread.
<b>Parameter</b>	thread: thread
<b>Return value</b>	N/A

## nwy\_resume\_thread

<b>Function</b>	void nwy_resume_thread(nwy_osiThread_t *thread);
<b>Description</b>	To resume a thread.
<b>Parameter</b>	thread: thread
<b>Return value</b>	N/A

## nwy\_send\_thread\_event

<b>Function</b>	bool nwy_send_thread_event(nwy_osiThread_t *thread, nwy_osiEvent_t *event, uint32 timeout);
<b>Description</b>	To send an event to the thread.
<b>Parameter</b>	thread: the thread that accepts events event: event Timeout: time-out period, 0 indicates that the function returns immediately after sending events.
<b>Return value</b>	Successful: true Failed: false

## nwy\_wait\_thread\_event

<b>Function</b>	bool nwy_wait_thread_event(nwy_osiThread_t *thread, nwy_osiEvent_t *event, uint32 timeout)
<b>Description</b>	The thread used to accept events.
<b>Parameter</b>	thread: current thread event: event timeout: time-out period, 0 indicates wait forever
<b>Return value</b>	Successful: true Failed: false

## nwy\_exit\_thread

<b>Function</b>	void nwy_exit_thread();
<b>Description</b>	To exist from a thread.
<b>Parameter</b>	Void
<b>Return value</b>	Void

## nwy\_get\_thread\_pendingevent\_cnt

<b>Format</b>	uint32_t nwy_get_thread_pendingevent_cnt(nwy_osiThread_t *thread);
<b>Description</b>	To obtain the number of events stored in the message queue.
<b>Parameter</b>	thread: thread pointer
<b>Return value</b>	The number of events stored in the current thread.

## nwy\_get\_thread\_spaceevent\_cnt

<b>Format</b>	uint32_t nwy_get_thread_spaceevent_cnt(nwy_osiThread_t *thread);
<b>Description</b>	To obtain the number of free events in the thread queue.
<b>Parameter</b>	thread: thread pointer
<b>Return value</b>	the number of free events in the thread queue

## nwy\_sleep

<b>Format</b>	void nwy_sleep(uint32 ms);
<b>Description</b>	Sleep delay
<b>Parameter</b>	sleep: delay time, unit: ms
<b>Return value</b>	NA

## nwy\_usleep

<b>Format</b>	void nwy_usleep(uint32 ms);
<b>Description</b>	Sleep delay
<b>Parameter</b>	sleep: delay time, unit: $\mu$ s
<b>Return value</b>	NA

## 2.5.5 mutex

mutex related APIs can be found in **nwy\_osi\_api.h**.

### nwy\_create\_mutex

<b>Function</b>	nwy_osiMutex_t *nwy_create_mutex();
<b>Description</b>	To initialize the mutually exclusive lock.

<b>Parameter</b>	Void
<b>Return value</b>	Successful: return the mutually exclusive lock Failed: NULL

### nwy\_lock\_mutex

<b>Function</b>	void nwy_lock_mutex(nwy_osiMutex_t *mutex, uint32 timeout);
<b>Description</b>	To add a lock.
<b>Parameter</b>	mutex: mutually exclusive lock timeout: time-out period, unit: ms (0: no timeout)
<b>Return value</b>	Void

### nwy\_unlock\_mutex

<b>Function</b>	bool nwy_unlock_mutex(nwy_osiMutex_t *mutex);
<b>Description</b>	To unlock.
<b>Parameter</b>	mutex: mutually exclusive lock
<b>Return value</b>	Successful: true Failed: false

### nwy\_delete\_mutex

<b>Function</b>	void nwy_delete_mutex(nwy_osiMutex_t *mutex);
<b>Description</b>	To delete a mutually exclusive lock
<b>Parameter</b>	mutex: mutually exclusive lock
<b>Return value</b>	Void

## 2.5.6 pipe

Pipe APIs can be found in `nwy_osi_api.h`.

### nwy\_osiPipe\_create

<b>Function</b>	nwy_osiPipe_t *nwy_osiPipe_create(unsigned size)
<b>Description</b>	To initialize a pipe.

<b>Parameter</b>	size: buffer size of the pipe.
<b>Return value</b>	Successful: return the created pipe. Failed: NULL

### nwy\_osiPipe\_delete

<b>Function</b>	void nwy_osiPipe_delete(nwy_osiPipe_t *pipe)
<b>Description</b>	To delete the pipe
<b>Parameter</b>	Pipe: pipe that is created.
<b>Return value</b>	void

### nwy\_osiPipe\_read

<b>Function</b>	int nwy_osiPipe_read(nwy_osiPipe_t *pipe, void *buf, unsigned size)
<b>Description</b>	To read data form the pipe.
<b>Parameter</b>	Pipe: pipe that is created. dst: buffer to be read data size: size of the data buffer.
<b>Return value</b>	Successful: number of bytes of data read

### osiPipeWrite

<b>Function</b>	int osiPipeWrite(osiPipe_t *pipe, const void *buf, unsigned size);
<b>Description</b>	To write data into the pipe.
<b>Parameter</b>	Pipe: pipe that is created. dst: buffer to be written data size: size of the data buffer.
<b>Return value</b>	number of bytes of data written.

## 2.5.7 Semaphore

Semaphore APIs can be found in `nwy_osi_api.h`.

### nwy\_semaphore\_create

<b>Function</b>	<code>nwy_osiSemaphore_t *nwy_semaphore_create(uint32 max_count, uint32 init_count);</code>
<b>Description</b>	To initialize the semaphore.
<b>Parameter</b>	max_count: maximum count of the semaphore init_count: initial count of the semaphore
<b>Return value</b>	Successful: return the semaphore Failed: NULL

### nwy\_semaphore\_acquire

<b>Function</b>	<code>bool nwy_semaphore_acquire(nwy_osiSemaphore_t *sem, uint32 timeout);</code>
<b>Description</b>	To acquire the semaphore.
<b>Parameter</b>	sem: semaphore timeout: time-out period, unit:ms (0 indicates no timeout)
<b>Return value</b>	Successful: true Failed: false

### nwy\_semaphore\_release

<b>Function</b>	<code>void nwy_semaphore_release(nwy_osiSemaphore_t *sem);</code>
<b>Description</b>	To release the semaphore.
<b>Parameter</b>	sem: semaphore
<b>Return value</b>	Void

### nwy\_semaphore\_delete

<b>Function</b>	<code>void nwy_semaphore_delete(nwy_osiSemaphore_t *sem);</code>
<b>Description</b>	To delete the semaphore.
<b>Parameter</b>	sem: semaphore
<b>Return value</b>	Void

## 2.5.8 Time

Time APIs can be found in **nwy\_api.h**.

### nwy\_set\_time

<b>Function</b>	void nwy_set_time(nwy_time_t *julian_time, char timezone)
<b>Description</b>	To set the time interface.
<b>Parameter</b>	julian_time: input time timezone: time zone
<b>Return value</b>	N/A.

### nwy\_get\_time

<b>Function</b>	int nwy_get_time(nwy_time_t *julian_time, char *timezone)
<b>Description</b>	To get the time interface.
<b>Parameter</b>	julian_time: time outputted timezone: time zone outputted
<b>Return value</b>	Failed: 0 Successful: 1

### nwy\_updatetime\_ntp

<b>Format</b>	int nwy_updatetime_ntp(char* url, unsigned long timeout, char* tz, unsigned char dst, nwy_update_time_cb cb_unc)
<b>Description</b>	To synchronize the network time.
<b>Parameter</b>	url: requested URL timeout: timeout period ranges from 1 to 30s. tz: selections of time zone, format "E/W digital", E: Eastern time zone (0-13), W: Western time zone (0-12) dst: daylight saving time switch 0: disable 1: enable cb_unc: result callback function
<b>Return value</b>	0: failed 1: successful

## nwy\_get\_time\_zone\_switch

<b>Format</b>	int nwy_get_time_zone_switch(nwy_time_zone_switch *status)
<b>Description</b>	To obtain the clock synchronization switch status.
<b>Parameter</b>	status: the obtained clock synchronization switch status NWY_TIME_ZONE_DISABLE = 0, NWY_TIME_ZONE_ENABLE = 1
<b>Return value</b>	Successful: NWY_SUCESS Failed: other values

## nwy\_set\_time\_zone\_switch

<b>Format</b>	int nwy_set_time_zone_switch(nwy_time_zone_switch status)
<b>Description</b>	To set the clock synchronization switch status.
<b>Parameter</b>	status: set the clock synchronization status NWY_TIME_ZONE_DISABLE = 0, NWY_TIME_ZONE_ENABLE = 1
<b>Return value</b>	Successful: NWY_SUCESS Failed: other values

## nwy\_get\_up\_time\_us

<b>Format</b>	int nwy_get_up_time_us(void)
<b>Description</b>	To obtain the device boot time.
<b>Parameter</b>	NA
<b>Return value</b>	the current time of the device, unit: $\mu$ s

## 2.5.9 Timer

Timer APIs can be found in **nwy\_osi\_api.h**.

## nwy\_timer\_init

<b>Function</b>	nwy_osTimer_t *nwy_timer_init(nwy_osiThread_t *thread, nwy_osiCallback cb, void *ctx)
<b>Description</b>	To initialize the timer.
<b>Parameter</b>	thread: thread used to process timer messages. cb: callback function of the timer



	*ctx: context of the callback function
<b>Return value</b>	Failed: NULL

### nwy\_timer\_deinit

<b>Function</b>	void nwy_timer_deinit(nwy_osiTimer_t *timer)
<b>Description</b>	To delete a timer
<b>Parameter</b>	timer: timer
<b>Return value</b>	N/A.

### nwy\_start\_timer

<b>Function</b>	bool nwy_start_timer(nwy_osiTimer_t *timer, uint32 ms)
<b>Description</b>	One-off timer
<b>Parameter</b>	timer: timer ms: time-out period (unit:ms)
<b>Return value</b>	Successful: true Failed: false

### nwy\_start\_timer\_periodic

<b>Function</b>	bool nwy_start_timer_periodic(nwy_osiTimer_t *timer, uint32 ms)
<b>Description</b>	Periodical timer
<b>Parameter</b>	timer: timer ms: time-out period (unit:ms)
<b>Return value</b>	Successful: true Failed: false

### nwy\_stop\_timer

<b>Function</b>	void nwy_stop_timer(nwy_osiTimer_t *timer)
<b>Description</b>	To stop the timer.
<b>Parameter</b>	timer: timer
<b>Return value</b>	Successful: true Failed: false